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# A Cultural Algorithm for the Two Variable Integer Programming Problem

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### 7 Abstract

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<sup>8</sup> A specific implementation of cultural algorithm is presented here for solving the following two

<sup>9</sup> variable integer programming problem with n constraints: Maximize or Minimizeare signed

<sup>10</sup> integers. A cultural algorithm consists of a population component almost identical to that of

<sup>11</sup> the genetic algorithm and, in addition, a knowledge component called the belief space. As the

<sup>12</sup> integer programming problem is a constrained optimization problem, the constraints including

<sup>13</sup> nonnegativity and integer restrictions are availed as the knowledge component and used to

<sup>14</sup> build the belief space.

Several computers codes using one or both methods have been written; and have successfully solved many real 21 problems. However, their performance has not been nearly as predictable as that of ordinary linear programming 22 codes-which are themselves rather unpredictable as regards running time (Beale, 1965). Martin et al. (1963) 23 Author ? ? : Department of Computer Science, Eritrea Institute of Technology, Asmara, The State of Eritrea, 24 North East Africa. E-mail: senanu.kumdev@gmail.com, ikgulam@gmail.com Author? : Department of 25 Mechanical & Vehicle Engineering, Adama Science & Technology University, Adama, Ethiopia, Africa. E-mail : 26 27 singh\_ajit\_pal@hotmail.com used a variant method of integer form called the "accelerated euclidean algorithms". 28 ??akin (1964) and ??riebeck (1964) have developed programs using a "branch and bound" method for mixed integer programming. Later Forest et al. ??1974), Tomlin (1971), ??riebeck (1966), ??akin (1965), Beale and 29 Small (1965), and others improved or refined the branch and bound approach of solving integer programming 30 31 problems in a number of ways. There are many survey articles and text books to describe the usage of refined and improved methods of using branch and bound approaches (Hansen, 1979; ??avindran, 1983a, 1985b) But 32 the most important facet of both Gomory's cutting plan approach and branch and bound approach is that they 33 can be applied only after obtaining noninteger solution using traditional optimization techniques like Simplex 34 Algorithms. 35 But the proposed cultural algorithmic approach directly searches the integer solution in the population space 36

which is a space obtained by narrowing the population space where the population space is obtained by the constraints of the problem.

Index terms— Cultural algorithm, Integer programming problem (IPP), Belief space, Genetic algorithm,
 Optimization.

In 1958, ??omory (1963a) devised a method, known as the "method for integer forms", for solving integer programming problems. In 1960, ??omory (1963b) devised another method for solving all integer linear programming problems.

<sup>39</sup> The implementation of the cultural algorithm is presented here to find ), (21 x x which satisfies all the 40 n constraints and yields the optimal value for Z. As IPP is a kind of constrained optimization problem, the 41 constraints including non-negativity constraints and integer restrictions are availed as knowledge component to build the belief space. A cultural algorithm, introduced by Reynolds (1994), and seen as extension to genetic 42 algorithm, is a computational model of cultural evolution process in nature where there is a knowledge component 43 in addition to population component. The knowledge component is used to build belief space. The best 44 individuals are selected from belief space using a fitness function. These best individuals are used to update 45 the belief space via a vote acceptance function. 46

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Generally cultural algorithms use five different kinds of knowledge component namely: normative, domain specific, situational, historical and topographical knowledge. The proposed cultural algorithm for solving two variable integer programming problems with n constraints uses a normative kind of knowledge gained from constraints including non-negativity and integer restrictions.

The proposed cultural algorithm for solving two variable integer programming problems uses the frame work for constrained optimization problem introduced by Carlos and Licardo (2002) to identify knowledge component and to build belief space. The algorithm is also using a variant of test bed introduced by Chang and Reynolds (1996) as the backbone of computational procedure.

# <sup>55</sup> 1 II. THE CULTURAL ALGORITHM FOR SLOVING TWO <sup>56</sup> VARIABLE INTERGER

#### 57 PROGRAMMIN PROBLEMS x

When the constrain i is asi i i c x b x a ? + 1 1 with ?, then i S can be defined as i i a c x ?? 1 0 irrespective of i b and if i i a c

is real, it should be rounded off to the immediate lower positive integer.

When the constraint i is asi i i  $c \ x \ b \ x \ a \ ? + 1 \ 1$  with ? , then  $i \ S \ can be defined as <math display="inline">? \ ? \ ? \ 1 \ x \ a \ c \ i \ i$  irrespective of  $i \ b \ and \ if \ i \ a \ c$ 

is real, it should be rounded off to the immediate higher positive integer . Note that if 0 = i a in the constraint

 $_{64}$   $\,$  i , then this constraint is ignored in defining space for 1 x .

65 ii. Definition of Population Space for 2

 $_{66}$   $\,$  x When the constraint i is asi i i c x b x a ? + 2 1 with ? , then i T can be defined as i i b c x ? ? 1 0  $_{67}$  irrespective of i a and if i i b c

68 is real, it should be rounded off to the immediate lower positive integer.

When the constraint i is asi i i c x b x a ? + 2 1 with ? , then i T can be defined as ? ? ? 1 x b c i i respective of i a and if i i b c

is real, it should be rounded off to the immediate higher positive integer. Note that if 0 = i b in the constraint i, thenx, {} g g g l l l x POP, 1, 2, ..., 2, 1, ) (1?? + + =

as the range of values between lowest ) (1 and greatest ) (g for 1

x will satisfy all the n constraints. This population space can also be stated as{ } n S S S x POP ? ? ? ,..., ) 75 (211 =

. Similarly, we build the population space for 2 x as { } n T T T x POP ? ? ? ,..., ) ( 2 1 2 = . ? Step 2: Initialization of Belief Space

78 When the objective function is to maximize ) (OC in achieving optimal  $2 \ 1 \ qx \ px +$ ) to build the belief space. 79 The fitness function which identifies and returns the optimal contributor is defined as follows:

80 Fitness Function:

81 When the objective function is to maximize 21 qx px + : The OC for 1 x is )) (max(1 x POP if 0? p; The

82 OC for 1 x is )) ( min( 1 x POP if 0 ? p ; The OC for 2 x is )) ( max( 2 x POP if 0 ? q ; The OC for 2 x is )) ( 83 min( 2 x POP if 0 ? q ;

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Similarly, when the objective function is to minimize 1 qx px + : The OC for 1 x is )) (min(1 x POP if 0 ? p ;; The OC for 1 x is )) (max(1 x POP if 0 ? p ; The OC for 2 x is )) (min(2 x POP if 0 ? q ; The OC for 2 x is )) (max(2 x POP if 0 ? q ;

When the objective function is to maximize  $2 \ 1 \ qx \ px +$ , the optimal contribution that 1

 $\begin{array}{ll} & \text{91} & \text{x can put in2 1 qx px + is [] p x OC * 1 )) ( and 2 x can put is [] q x OC * 2 )) ( . Here if [] [] q x OC p x \\ & \text{92} & \text{OC * 2 * 1 )) ( )) ( ? then 1 \end{array}$ 

x can be greater contributor than 2 x, otherwise 2

x is greater contributor than 1 x in achieving optimal 2 1 qx px + .

Similarly, when the objective function is to minimize 2 1 qx px + , and if ] )) ( [ ] )) ( [ \* 2 \* 1 q x OC p x OC ? then 2

 $_{\rm 97}$   $\,$  x can be greater contributor than 1 x , otherwise1  $\,$ 

 $_{\rm 98}$   $\,$  x is greater contributor than 2 x in achieving optimal . This indicates the population space of 1

x and/or 2 x is unbounded or indefinite. We adapt the following rules in such instances.

100 1. If the population space of both 1

101 x and 2 x are bounded/definite and non-null, we identify the GC as discussed earlier and make use of this 102 in building belief space. 2. If the population space of any one variable is found to be unbounded/indefinite or 103 null, we consider the other variable as GC in building belief space irrespective of the unbounded/indefinite or

104 null population space of former variable.

## <sup>105</sup> 3 If the population spaces of both variables are

106 found to be unbounded/indefinite or null, then this is indication that there is inability in building the belief

space. With such population spaces, we declare that the problem has infeasible or unbounded solution space.
 When the GC is identified evidently, we believe that the

```
(109) )) (max( GC POP is playing the greatest role than all other components in the population space in achieving
the maximum 1 qx px + and )) (min(
```

111 GC POP is playing the greatest role than all other components in population space in achieving the minimum 112  $2 \ 1 \ qx \ px +$ . Note that, here, GC is either 1

113 x or 2

114 x. Thus we define the belief space ) (i BLF , ( i is initially 0), as follows:

Building Belief Space: Case I: When 1

116 x is found to be GC and the objective function is to maximize 21 qx px + : ) , ( ) ( 21 x x i BLF = such 117 that: )) ( max( 11 x POP x = ; ; 2 B x ? where B is a set of integers which is intersection of n B B B

118 ,..., 2 1 and i B can be defined asi i i b x a c x ) (12?? if the constraint i is as i i i c x b x a ? + 2 1 with 119 ? and as i i i b x a c x ) (12?? if the constraint i as i i i c x b x a ? + 2 1 with ? where )) (max(11 x POP 120 x = .

If the constraint i is asi i i c x b x a ? + 2 1 with of ?, then i i i b x a c) (1?

should be rounded off to the immediate lower positive integer and it is asi i i c x b x a ? + 2 1 with ? , then i i i b x a c

124 ) (1? should be rounded off to the immediate higher positive integer.

125 Case II : When 1

 $\begin{array}{ll} x \mbox{ is found to be GC and the objective function is to minimize2 1 qx px +: ) , () (21 x x i BLF = such 127 that: )) (min(11 x POP x = ; ; 2 B x ? where B is a set of integers which is intersection of n B B B ,..., ,21 \\ \end{array}$ 

and i B can be defined as i i b x a c x ) (12?? if the constraint i is as i i i c x b x a? + 21

with ? and asi i i b x a c x ) (12? ? if the constraint i as i i i c x b x a ? + 21 with ? where )) (min(11 x POP x = .

131 If the constraint i is asi i i c x b x a ? + 2 1 with of ?, then i i i b x a c) (1?

should be rounded off to the immediate lower positive integer and it is asi i i c x b x a ? + 2 1 with ? , then i i i b x a c ) ( 1 ?

should be rounded off to the immediate higher positive integer. x is found to be GC and the objective function is to maximize 1 qx px + :), () (2 1 x x i BLF = such that: ; 1 B x ?)) (max(2 2 x POP x = ; where B is a set of integers which is intersection of n B B B

137 ,..., 2 1 and i B can be defined as i i a x b c x ) (21?? if the constraint i is as i i i c x b x a ? + 2 1

with ? and asi i i a x b c x ) (21?? if the constraint i as i i i c x b x a ? + 21 with ? where )) (max(12 x POP x = . If the constraint i is as i i i c x b x a ? + 21 with of ?, then i i i a x b c ) (2?

should be rounded off to the immediate lower positive integer and it is asi i i c x b x a ? + 2 1 with ? , then i i i a x b c ) ( 2 ?

should be rounded off to the immediate higher positive integer.

143 Case IV: When 2

144 x is found to be GC and the objective function is to minimize 1 qx px + : ), () (2 1 x x i BLF = such145 that: ; 1 B x? )) (min(2 2 x POP x =; where B is a set of integers which is intersection of n B B B,..., 21

and i B can be defined asi i i a x b c x ) (21?? if the constraint i is as i i i c x b x a? + 21 with? and as i i i a x b c x ) (21?? if the constraint i as i i i c x b x a? + 21 with? where )) (min(12 x POP x = . If the constraint i is as i i i c x b x a? + 21 with of?, then i i i a x b c ) (2?

the constraint i is as i i i c x b x a ? + 2 1 with of ?, then i i i a x b c) (2? should be rounded off to the immediate lower positive integer and it is asi i i c x b x a ? + 2 1 with ?, then i i i a x b c) (2?

should be rounded off to the immediate higher positive integer.

Note that, hereafter, we use the terms greater contributor ) (GC and lower contributor ) (LC , instead of 1 x and 2

x. If 1 x is found to be GC in the earlier step then 2

155 x is LC, otherwise 1 x is LC and 2 x is GC.

## <sup>156</sup> 4 ? Step 3: Evaluation of Space

The moment we arrive to evaluate the current belief space, GC is fixed with one single best component and LC lies in the set B. Now lets search the best component for LC from B which may produce the optimal value of )) (i BLF Z = and classify this outcome of evaluation as non-futile.

There may be an uncommon situation here while evaluating current belief space in search of the best component of LC that suits with the best component of GC which is already fixed while defining the current belief space. The unusual situation is that the set B identified for LC while defining the current belief space may be a null set. This indicates that there exist no single component in population space of LC to accept the best component chosen for GC to build the current belief space. In such situations, we assume that the mission with current belief space is failed and classify this outcome of evaluation as futile.? Step 4: Vote Acceptance Function If the

166 )) 1 ( ( )) ( ? ? = i BLF Z i BLF Z

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when the objective function is to maximize x are the best components used for GC and LC in calculating

168 ))1 (? = i BLF Z. Similarly, If the )) 1 (()) (?? = i BLF Z i BLF Z

when the objective function is to minimize

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The vote acceptance function rejects the outcome of evaluation in all other circumstances except the above explained situations. Thus the function rejects the outcome of evaluation and suggest to reproduce the population space in all the following instances: IF WE ARE WORKING WITH INITIAL BELIEF SPACE (THAT IS ) (i BLF WHERE 0 = i ) IF THE OUTCOME OF EVALUATION OF ) (i BLF WAS FOUND TO BE FUTILE. IF )) 1 ( ( )) ( ( ? ? i BLF Z i BLF Z WHEN THE OBJECTIVE FUNCTION IS TO MAXIMIZE 2 1 qx px Z + = . )) 1 ( ( )) ( ( ? ? i BLF Z i BLF Z WHEN THE OBJECTIVE FUNCTION IS TO MINIMIZE 2 1 qx px Z + = .

? Step 5: Modification in the Belief Space When the vote acceptance function suggests to reproduce population space, we modify the current belief space ) (i BLF to get ) 1 ( + i BLF by the modifying the GC . Note that the GC is one fixed component and LC lies in the set B in the current belief space. We now modify this belief space by adjusting the component fixed to the GC . Based on this modified GC , we define once again the set B where LC lies, which along with fixed modified component of GC forms new belief space ) 1 ( + i BLF . Thus the modification to GC is brought as follows:

185 Case I: If the objective function is to maximize such that GC is the component codified above and LC belongs

to the set B defined above. This modified belief space is then submitted to the promote influence function which
 will deicide the further course on whether this space is to be evaluated or not. a. Step 6: Promote Influence Function <sup>1 2 3</sup>



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Figure 1: A 3

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Case II: If the objective function is to maximize and the co-efficient of LC in ob 2 1 qx px + function is less than zero or if the objective function is to minimize 2 1 qx and the px +coefficient ofLCin objective function is greater than zero , the smallest component of B is considered as the best component for LC .

Find the value of

 $\begin{array}{c} {\rm components\ of}\\ 2\ 1\ qx\ px\ + & {\rm and\ the\ co-efficient\ of\ LC\ in\ objective}\\ {\rm function\ is\ greater\ than\ zero\ or\ if\ the\ objective\ function\ is}\\ {\rm to\ minimize\ } & 2 & {\rm and\ the\ co-efficient\ of\ LC\ in}\\ & 1 & \\ & qx & \\ & px & \\ & + & \\ {\rm objective\ function\ is\ less\ than\ zero,\ then\ the\ largest}\\ {\rm component\ of\ B\ is\ considered\ as\ the\ best\ component}}\end{array}$ 

for LC .

### Figure 2:

2 1 qx px +		and the co-efficient of GC in objectiv	e
function is greater than zero o	or if the objective funct	ion is	
to minimize		2 1  qx px +	
belief space		BLF (	) as sho
		+	1 in $1$
		i	section
			2.2.2
Building Belief Space.			
0	Now the	e new belief space	BLF( + i
(	, 1 )		
	X		
	2		

х

Figure 3:

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### 189 .1 III.

## 190 .2 CONCLUSION

A specific implementation of cultural algorithm is presented using the computational model of cultural evolution 191 process to solve two variable IPPs. Identifying formative knowledge sources in IPPs, the belief space is built 192 in addition to the traditional framework of genetic algorithms. Whilst the existing approaches like Gomery's 193 and Branch and Bound need non-integer solution produced by traditional optimization methods like simplex 194 algorithms, the proposed algorithm steer clear of the computational load of solving linear programming problem 195 relaxations. Comparing the complexity of Gomery's and Branch and Bound approaches, searching global optimal 196 solution using proposed cultural algorithm is especially slender. This implementation can be extended for solving 197 IPPs with any number of decision variables and constraints with signed integers in future. 198

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