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5 Abstract

⁶ Images are often corrupted by impulse noise, also known as salt and pepper noise. Salt and

7 pepper noise can corrupt the images where the corrupted pixel takes either maximum or

8 minimum gray level. Amongst these standard median filter has been established as reliable -

⁹ method to remove the salt and pepper noise without harming the edge details. However, the

¹⁰ major problem of standard Median Filter (MF) is that the filter is effective only at low noise

¹¹ densities. When the noise level is over 50

12

Index terms— A Abstract -Images are often corrupted by impulse noise, also known as salt and pepper noise. Salt and pepper noise can corrupt the images where the corrupted pixel takes either maximum or minimum gray level. Amongst these standard median filter has been established as reliable -method to remove the salt and pepper noise without harming the edge details. However, the major problem of standard Median Filter (MF) is that the filter is effective only at low noise densities.

When the noise level is over 50% the edge details of the original image will not be preserved by standard 19 20 median filter. Adaptive Median Filter (AMF) performs well at low noise densities. In our proposed method, 21 first we apply the Stationary Wavelet Transform (SWT) for noise added image. It will separate into four bands 22 like LL, LH, HL and HH. Further, we calculate the window size 3x3 for LL band image by Reading the pixels from the window, computing the minimum, maximum and median values from inside the window. Then we 23 24 find out the noise and noise free pixels inside the window by applying our algorithm which replaces the noise pixels. The higher bands are smoothing by soft thresholding method. Then all the coefficients are decomposed 25 by inverse stationary wavelet transform. The performance of the proposed algorithm is tested for various levels 26 of noise corruption and compared with standard filters namely standard median filter (SMF), weighted median 27 filter (WMF). Our proposed method performs well in removing low to medium density impulse noise with detail 28 preservation up to a noise density of 70% and it gives better Peak Signal-to-Noise Ratio (PSNR) and Mean square 29 30 error (MSE) values.

31 mpulse noise may often corrupt the images, which is known as salt and pepper noise. A standard signal processing requirement is to remove randomly occurring impulses without disturbing the edges. It is well known 32 that linear filtering techniques fail when the noise is non-additive and are not effective in removing impulse noise. 33 This lead researchers to make use of the nonlinear signal processing techniques. Based on two types of image 34 models corrupted by impulse noise, two new algorithms for adaptive median filters are presented in Ref. [1]. these 35 have variable window size for removal of impulses while preserving sharpness. The first one, Author : Research 36 Scholar, Department of Computer Science, S.V. University, Tirupati -517 502, Andhra Pradesh, India E-mail 37 : naveennsvu@gmail.com Author : Professor, Department of Computer Science, S.V. University, Tirupati -517 38 502, Andhra Pradesh, India E-mail : drsramakrishna@yahoo.com called the ranked-order based adaptive median 39 filter (RAMF), is based on a test for the presence of impulses in the center pixel itself followed by the test for the 40 41 presence of residual impulses in the median filter output. The second one, called the impulse size based adaptive 42 median filter (SAMF), is based on the detection of the size of the impulse noise.

A new impulse noise detection technique for switching median filters was described in Ref. [2], which is based on
the minimum absolute value of four convolutions obtained using one-dimensional Laplacian operators. Extensive
simulations show that the proposed filter provides better performance than many of the existing switching median
filters with comparable computational complexity.

Srinivasan et al. [3], proposed a new decisionbased algorithm for the restoration of images that are highly
corrupted by impulse noise. They reported significantly better image quality than a standard median filter
(SMF), adaptive median filters (AMF), threshold decomposition filter (TDF), cascade, and recursive nonlinear

50 filters. Unlike other nonlinear filters, this method, removes only corrupted pixel by the median value or by its 51 neighboring pixel value.

Previously, many linear and nonlinear filtering techniques have been described to remove impulse noise. 52 However, these filters often bring along blurred and distorted image of details. A detail preserving filter for 53 impulse noise removal was proposed by Dagao Duan et al. [4]. on the basis of the Soft-Switching Median (SWM) 54 filter. Moreover, Eduardo Abreu [5] reported a new framework for removing impulse noise from images, in which 55 the nature of the filtering operation is conditioned on a state variable defined as the output of a classifier that 56 operates on the differences between the input pixel and the remaining rank-ordered pixels in a sliding window. As 57 part of this framework, several algorithms are examined, each of which is applicable to fixed and random-valued 58 impulse noise models. Also, Chenhen et al. [6] reported a novel nonlinear filter, called tri-state median (TSM) 59 filter, for preserving image details while effectively suppressing impulse noise. The standard median (SM) filter 60 and the center weighted median (CWM) filter into a noise detection framework to determine whether a pixel is 61 corrupted, before applying filtering unconditionally. 62 To restore images corrupted by salt-pepper impulse noise, a new median-based filter such as progressive 63

switching median (PSM) filter was presented in Ref. [7]. It was developed on the basis of the following two main points: 1) switching scheme an impulse detection algorithm is used before filtering, thus only a proportion of all the pixels will be filtered and, 2) progressive methods both the impulse detection and the noise filtering procedures are progressively applied through several iterations.

A generalized framework of median based switching schemes, called multi-state median (MSM) filter is 68 presented in Ref. [8]. By using simple thresholding logic, the output of the MSM filter is adaptively switched 69 among those of a group of center weighted median (CWM) filters that have different center weights. A novel 70 switching-based median filter with incorporation of fuzzy-set concept, called the noise adaptive soft-switching 71 median (NASM) filter [9], to achieve much improved filtering performance in terms of effectiveness in removing 72 impulse noise while preserving signal details and robustness in combating noise density variations. Also, Luo 73 et al [10] designed a new efficient algorithm for the removal of impulse noise from corrupted images while 74 preserving image details. It was interpreted on the basis of the alpha-trimmed mean, which is a special case of 75 the order-statistics filter. The SWT provides efficient numerical solutions in the signal processing applications. 76 It was independently developed by several researchers and under different names, e.g. the un-decimated wavelet 77 transform, the invariant wavelet transform and the redundant wavelet transform. The key point is that it gives a 78 79 better approximation than the discrete wavelet transform (DWT) since, it is redundant, linear and shift invariant. 80 These properties provide the SWT to be realized using a recursive algorithm. Thus, the SWT is a very useful algorithm for analyzing a linear system. 81

A brief description of the SWT is presented here. It shows the computation of the SWT of a signal , where , and are called the detail and the approximation coefficients of the SWT. The filters and are the standard lowpass and highpass wavelet filters, respectively. In the first step, the filters and are obtained by upsampling the filters using the previous step (i.e. and). .

⁸⁶ 1 Block Diagram

87 X(i-1,j-1)

 $\begin{array}{lll} & X(i-1,j) \ X(i-1,j+1) \ X(i,j-1) \ X(i,j) \ X(i,j+1) \ X(i+1,j+1) \ X(i+1,j+1) \ Table.1: \ 3 \ x \ 3 \ Filtering window \\ & with \ X(i,j) \ as center pixel \ 1. Set the minimum window size w=3; \ 2. Read the pixels from the sliding window and \\ & store it in(S). \ 3. \ Compute minimum, maximum and median value inside the window. \ 4. If the center pixel in the \\ & window \ X(i,j), is such that \ min<X(i,j)<max, then it is considered as uncorrupted pixel and retained. Otherwise \\ & go to step \ 5. \ 5. \ Select the pixels in the window such that \ min<Sij<max if number of pixels is less than \ 1 \ then \\ & increase the window size \ by \ 2 \ and \ go to \ step \ 2, else \ go to \ step \ 6. \ 6. \ Difference \ of each pixel inside the window \\ & with \ the median \ value \ is calculated \ as \ x \ and \ applied \ to \ robust \ influence \ function. \end{array}$

where is outlier rejection point which is given by where the maximum is expected outlier and is given by where the local is estimate of the image standard deviation and is a smoothening factor. Here =0.3 is taken for medium smoothening. 7. Pixel is estimated using equation (??) and (??) For all higher bands (LH, HL and HH) the denoising can be achieved by applying a thresholding operator to the wavelet coefficients in the transform domain followed by reconstruction of the signal to the original image in spatial domain. In our proposed method, soft shrinkage and Median Absolute Difference (MAD) are used. The scaled MAD noise estimator is calculated by (6).

where X is the high frequency sub-bands coefficients. From the estimated noise, the non linear threshold T is calculated by (7) where N is the size of the high frequency subband array. Then the soft thresholding is applied to remove the noise and the soft shrinkage rule is defined by (8). Finally, the noise free image is obtained by taking then inverse SWT The noise free sub-bands are obtained by using adaptive thresholding. Finally, the noise free image is obtained by taking the inverse SWT using the modified high frequencies sub-bands and the low frequency sub band of SWT.

The proposed algorithm tested for 256x256 images. It is tested for various levels of noise values and also compared with Standard median filter (SMF). Figure 2 shows the de-noising performance of the proposed algorithm. Table 2 show the PSNR values of the proposed method and based soft shrinkage and SWT method with different noise variance. Figure $\ref{eq:shows}$ shows the comparison of PSNR value for median filter and our proposed method. $^{1-2}$



Figure 1: An

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Figure 2:

Figure 3: Fig 1 :

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JTRODUCTION

Figure 4:

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Figure 5: Figure 2 :

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March 46 Noise Level Median Filter Proposed Method 2027.2631.033022.5629.69 4018.3328.0526.355015.0712.224.27 60 709.67 21.8635302520Median Filter 15Proposed 10Method 50 30 40 5060 7020

Figure 6: Table 2 :

113 .1 March

- 114 In this work, we presented the image denoising based on Stationary Wavelet transform (SWT) and soft threshold
- method is presented. Experimental results show that the proposed method restore the original image much better
- than standard non linear median-based filters and some of the recently proposed algorithms. The proposed filter
- 117 requires less computation time compared to other methods. The visual quality results clearly shows the proposed 118 filter preserve fine details such as lines and corners satisfactorily. This filter can be further improved to apply for
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