

# GLOBAL JOURNAL

## OF COMPUTER SCIENCE AND TECHNOLOGY : E

# NETWORK, WEB & SECURITY

DISCOVERING THOUGHTS AND INVENTING FUTURE

### HIGHLIGHTS

Coverage of Wireless Sensors

Adaptive Hybrid Routing Topology

Data Provenance Verification

Mobile Application Development

Computer Server Farm

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## CONTENTS OF THE VOLUME

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- i. Copyright Notice
- ii. Editorial Board Members
- iii. Chief Author and Dean
- iv. Table of Contents
- v. From the Chief Editor's Desk
- vi. Research and Review Papers
  
- 1. Smart Connect Using Cellular Technology. *1-4*
- 2. Controlling the Coverage of Wireless Sensors Network Using Coverage in Block Algorithm. *5-8*
- 3. ESAHR: Energy Efficient Swarm Adaptive Hybrid Routing Topology for Mobile Ad Hoc Networks. *9-15*
- 4. Authorised Secure Host Communication under Data Provenance Verification-A Signcryption Based Contract Signing Protocol. *17-25*
- 5. GSM Based Operating of Embedded System Cloud Computing, Mobile Application Development and Artificial Intelligence Based System. *27-31*
  
- vii. Auxiliary Memberships
- viii. Process of Submission of Research Paper
- ix. Preferred Author Guidelines
- x. Index



## Smart Connect Using Cellular Technology

By Ms. Priyanka V. Kampasi & Y.C. Kulkarni

*Bharati Vidyapeeth's College of Engineering/IT, Pune, India*

**Abstract** - Technical developments in computer hardware and software make it possible to introduce automation into virtually all aspects of human-machine systems. Automation has made Software applications much more efficient to use. This paper proposes that automation can be applied to desktop sharing in which a system can operate automatically anywhere in the world using GSM technology & VIRTUAL LAN concept.

The proposed system will be used to make the purpose of data access simpler, keeping in mind the needs of the IT industries. Through this system, automated desktop sharing can be implemented with effective cause. Today's desktop conferencing and groupware software often assume a serial work model in which information (pictures, documents, presentations) are prepared by one person and then disseminated to others for comments, revision, or review. However, many types of collaborative work are much more parallel, with many people viewing, updating, and adding information concurrently across cross-platform display sharing between Mac OS, Windows, and UNIX operating systems. The current EMSL Televiewer prototype supports display sharing of application windows, screen regions, and desktops. This system proposes enhancements to the EMSL Televiewer that will provide collaborative annotations over the display, shared mouse cursors, pointer, high performance data compression, and session recording capabilities. When completed, the EMSL Televiewer will provide researchers and the scientific community a powerful tool that can by itself open up many new avenues for collaboration and will fit well with other tools to provide a comprehensive collaborative environment.

**Keywords** : Cell Phone, Desktop Sharing, Encryption, GSM, Microcontroller.

**GJCST-E Classification** : C.2.1



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## I. INTRODUCTION

The concept of Desktop Sharing has revolutionized the work of IT professionals immensely. While sitting at home or while roaming, an IT professional can work on his office computer anytime. The Computer system in the office can be accessed by the employee anywhere. Yes, of Course there are security considerations that must be met. That is, the authenticity of the person requesting access to the workplace computer. Earlier even though a person could remotely access his/her office computer but still he/she required a desktop computer or a laptop. The Goal of designing this application is for the benefit of industry people by allowing them multi-sharing of the computer screen for their assignments through cellular technology like a Cell Phone. It requires a PC with a modem setup. The

Computer/laptop contains important data or information. This information can be accessed by the user anywhere anytime through her mobile phone. The Cell Phone must be Internet enabled. When a request is send by the cell phone to the respective modem which is received using the GSM system, it shall respond back by sending an acknowledgment message asking password so as to confirm that an authentic user has made the request.

As soon as the correct password is received as a response to the request, the system shall generate 4-digit conformation code for establishing the connectivity. As soon as the system is connected, the data transfer can take place. For providing security to the data transmission, SHA-1 algorithm is used.

The system is basically focused for those people who travel around the globe and need to be consistently connected to their workplace or home at the same time.

The proposed system has a great potential and it will benefit the masses for a long time.

Everybody these days possesses a Mobile Phone. As it is small in size and portable, it become a smarter choice for accessing the remote desktop than a PC or a laptop. This paper proposes the use of Mobile Phones (equipped with Internet features) by the IT professionals to access their office computers after proper authentication check.

The overall system will require hardware components like a Modem, Microcontroller, Microprocessor and a USB Port to accomplish this task. For secure transmission of data between the cellular device and the PC, encryption algorithm (SHA 1) will be used.

Apart from this if ROBOT APIs are used then we can use our Mobile phone as a remote control for switching on or off the lights, adjusting the thermostat of our AC. It could also be used for indicating the temperature in high temperature zones like Nuclear Reactors.

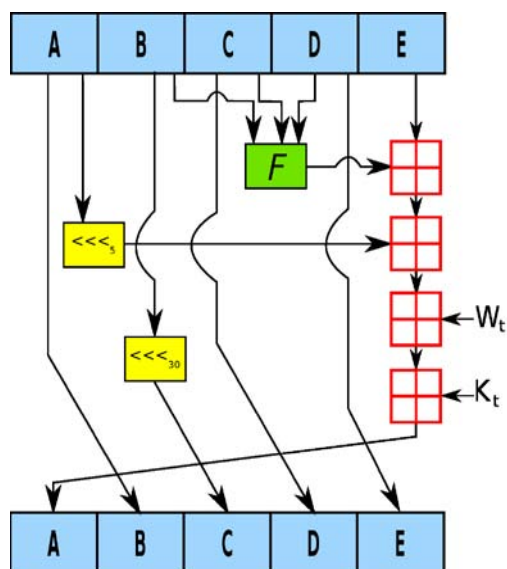
The whole application is divided into modules according to their functionalities. The output of one module is input for the next module. Intended Audience and Reading Suggestions This document is intended for the persons in the following categories Students doing Graduation in Computers. Internal and External guide.

Most of the industries need it for their project development.

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## a) The SHA-1 hash function

SHA-1 produces a 160-bit message digest based on principles similar to those used by Ronald L. Rivest of MIT in the design of the MD4 and MD5 message digest algorithms, but has a more conservative design. The original specification of the algorithm was published in 1993 as the *Secure Hash Standard*, FIPS PUB 180, by US government standards agency NIST (National Institute of Standards and Technology). This version is now often referred to as *SHA-0*. It was withdrawn by NSA shortly after publication and was superseded by the revised version, published in 1995 in FIPS PUB 180-1 and commonly referred to as *SHA-1*. SHA-1 differs from SHA-0 only by a single bitwise rotation in the message schedule of its compression function; this was done, according to NSA, to correct a flaw in the original algorithm which reduced its cryptographic security. However, NSA did not provide any further explanation or identify the flaw that was corrected. Weaknesses have subsequently been reported in both SHA and SHA-1. SHA-1 appears to provide greater resistance to attacks, supporting the NSA's assertion that the change increased the security.



One iteration within the SHA-1 compression function:

A, B, C, D and E are 32-bit words of the state;

$F$  is a nonlinear function that varies;

$n$  denotes a left bit rotation by  $n$  places;

$n$  varies for each operation;

$W_t$  is the expanded message word of round  $t$ ;

$K_t$  is the round constant of round  $t$ ;

Denotes addition modulo 232

## II. LITRATURE SURVEY

Desktop sharing commonly refers to a remote frame buffer technology. Desktop sharing allows a user to send screen data to be drawn elsewhere and receive input remotely. Its applications vary from remote system

administration to accessing virtual machines. There has been much research concerning the use of desktop sharing as a platform for collaboration. A few useful features appear in several papers.

The BASS Application Sharing System established the idea of applying a secondary protocol to re-encode video and stream it separately from the frame buffer for any video playing on the screen. Additionally the sharing system supports per-application sharing by removing all non-application specific information from the remote frame buffer. In one system researchers enhanced the Virtual Network Computing (VNC) protocol by adding an additional layer of authentication to allow for view-only or normal interactivity connections.

Systems that support multicast (multiple people only seeing one screen) tend to use the Binary Floor Control Protocol to determine controllability of the screen at any one point in time. There are also other papers of interest that cover non-desktop sharing collaboration. For example, research on remote pair programming, where two users work on the same code at the same time using shared cursors and synchronized codebases, differs from desktop sharing because both users are still seeing different desktops. Instead of actually visualizing the other collaborator's desktop, a user of the Sangam tool has a synchronized view and cursor with the other collaborators. This approach works well in very specialized environments such as programming Integrated Development Environments (IDEs) but lacks usability in more general scenarios. Unfortunately no hard research has been done on the efficacy of the technique but it is important to remember that desktop sharing is just one facet of collaboration technology.

Help desk is a generic name typically associated with an end-user support center. Prior to the creation of a dedicated help desk, end-users often resorted to contacting a friend or colleague for assistance. Today's savvy technology managers realize that it is critical to transform outdated "help desks," which rely primarily on telephone communications, into efficiently managed "service desks" that efficiently and economically accommodate multiple forms of interaction - from voice and data to email and instant messaging. They also understand that by transitioning to self-assist and remote incident resolution they can reduce service desk operational costs by half, while dramatically improving the quality of service provided.

Although the telephone is the preferred method of seeking support, end-users can encounter frustration when calling the help desk. End-users often lack confidence that they will be able to adequately describe the issue they are experiencing or fear embarrassment for their lack of application and or computer knowledge and skills. This can lead to confusion and

misinterpretation for the support specialist as they attempt to resolve the issue. Concern over a language barrier is a potential drawback of phone support as well. The end-user may become frustrated and abandoned the call before their issue is resolved if they're unable to understand a support specialist due to a thick accent.

In order to overcome such problem, the Help Desk can capture the customers desktop and solve the problem themselves.

### III. SYSTEM ARCHITECTURE

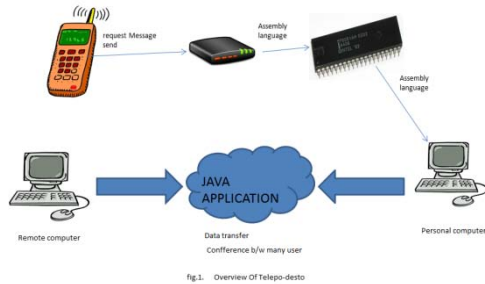


Fig. 1

A user has to send an SMS by the cell phone to the home server. It will be received through hardware modules like modem, microcontroller and a microprocessor. The system responds back by sending an acknowledgment message asking user to prove his/her authenticity.

In case of authentic password reception, the system generates a onetime password for the user to establish the connectivity. As soon as the system is connected, the data transfer can take place. For providing security to the data transmission, a very powerful encryption algorithm is used.

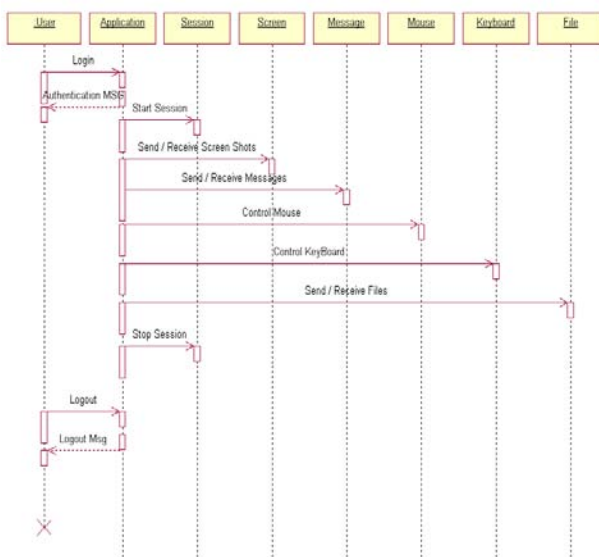


Fig. 2 : Sequence Diagram

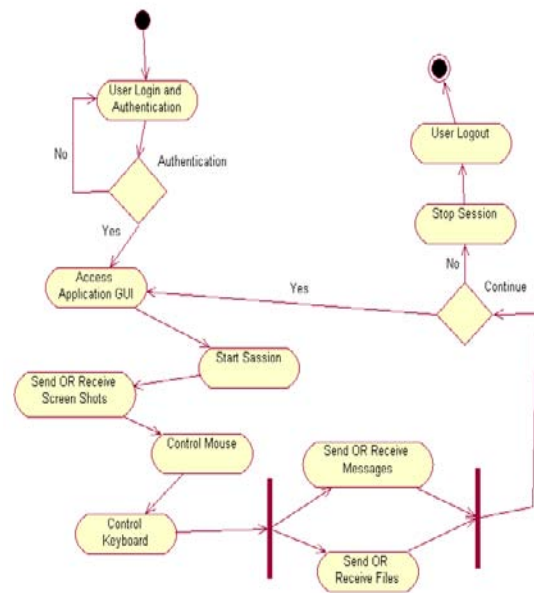


Fig. 3 : Use case diagram

### IV. ADVANTAGES

1. Anyone can access data from a PC anywhere and anytime by simply sending an SMS.
2. It saves money by lowering your monthly utility bills.
3. Easy to operate and use as Mobile Phones are extensively used.
4. Has negligible portability issues as Cell Phones easily fit in pockets.

### V. DISADVANTAGES

1. The energy required to run the devices .This problem can be removed by using solar technology to run the system.
2. Installation will need expertise person the local resident will face a problem in installation.
3. There is maintenance of this system is required as this is a new technology and have potential risks. Regular checkup of the security and other critical operations are necessary for such new technology.

### VI. CONCLUSION

In conclusion, I feel that the proposed system has a great potential in revolutionizing the concept of Desktop Sharing. As Mobile phones are small in size and easily portable, they become a smarter choice for accessing the remote desktop than a PC or a laptop. They can be easily carried and handled by their users. They are a smarter means of working on Remote Systems than a traditional desktop computer or a laptop. Also a cell phone can become a remote control for its users in switching on or off the light bulbs or also act as an indicator showing temperature readings in high temperature zones.



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# Controlling the Coverage of Wireless Sensors Network Using Coverage in Block Algorithm

By Rashid Azim

*ICMS University Campus, Hayyatabad*

**Abstract** - This research investigate the modeling of Blocks, Present in the sensing field and its impact in the computation of coverage path in wireless sensor networks (WSNs). The solutions of these problems are proposed using techniques from Approximation algorithm. In order to accomplish the designated task successfully, sensors need to actuate, compute and disseminate the acquired information amongst them. Intuitively, coverage denotes the quality of sensing of a sensor node. While a sensor senses. It needs to communicate with its neighboring sensor nodes in order to disseminate the acquired data. That is where connectivity comes in to place. In fact, coverage and connectivity together measure the quality of service (QoS) of a sensor network. Coverage and connectivity in wireless sensor networks are not unrelated problems. Therefore, the goal of an optimal sensor deployment strategy is to have a globally connected network, while optimizing coverage at the same time. By optimizing coverage, the deployment strategy would guarantee that optimum area in the sensing field is covered by sensor, as required by the underlying application, whereas by ensuring that the network is connected, it is ensured that the sensed information is transmitted to other nodes and possibly to a centralized base station (called sink) which makes valuable decision for the application. Many recent and ongoing research in sensor networks focus on optimizing coverage and connectivity by optimizing node placement strategy, minimizing number of nodes to guarantee required degree of coverage, maximizing network lifetime by minimizing energy usage, computing the most and least sensed path in the given region and so on. To solve these optimizing problems related to coverage, exiting research uses mostly probabilistic technique based on random graph theory, randomized algorithm, computational geometry, and so on. Of particular interest to us is the problem of computing the coverage in block (CIB), where given a set of homogeneous sensors deployed in a field and the initial location of an agent that needs to move through the field, determine the path that is most protected by the sensors.

*GJCST-E Classification : C.2.1*



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**Abstract** - This research investigate the modeling of Blocks, Present in the sensing field and its impact in the computation of coverage path in wireless sensor networks (WSNs). The solutions of these problems are proposed using techniques from Approximation algorithm. In order to accomplish the designated task successfully, sensors need to actuate, compute and disseminate the acquired information amongst them. Intuitively, coverage denotes the quality of sensing of a sensor node. While a sensor senses. It needs to communicate with its neighboring sensor nodes in order to disseminate the acquired data. That is where connectivity comes in to place. In fact, coverage and connectivity together measure the quality of service (QoS) of a sensor network. Coverage and connectivity in wireless sensor networks are not unrelated problems. Therefore, the goal of an optimal sensor deployment strategy is to have a globally connected network, while optimizing coverage at the same time. By optimizing coverage, the deployment strategy would guarantee that optimum area in the sensing field is covered by sensor, as required by the underlying application, whereas by ensuring that the network is connected, it is ensured that the sensed information is transmitted to other nodes and possibly to a centralized base station (called sink) which makes valuable decision for the application. Many recent and ongoing research in sensor networks focus on optimizing coverage and connectivity by optimizing node placement strategy, minimizing number of nodes to guarantee required degree of coverage, maximizing network lifetime by minimizing energy usage, computing the most and least sensed path in the given region and so on. To solve these optimizing problems related to coverage, exiting research uses mostly probabilistic technique based on random graph theory, randomized algorithm, computational geometry, and so on. Of particular interest to us is the problem of computing the coverage in block (CIB), where given a set of homogeneous sensors deployed in a field and the initial location of an agent that needs to move through the field, determine the path that is most protected by the sensors.

## I. INTRODUCTION

The emerging field of wireless sensor networks combines sensing, computation, and communication into a single tiny device. Through advanced mesh networking protocols, these devices form a sea of connectivity that extends the reach of cyberspace out into the physical world. As water flows to fill every room of a submerged ship, the mesh networking connectivity will seek out and exploit any possible communication path any single device are

minimal, the composition of offers radical new technological possibilities.

The power of wireless sensor networks lies in there ability to deploy large numbers of tiny nodes that assemble and configure themselves. Usage scenarios for these devices computing environments, to in situ monitoring of the health of structures or equipment.

While often referred to as wireless sensor networks, they can also control actuators that extend control from cyberspace into the physical world.

The most straight forward application of wireless sensor network technology is to plant could be easily monitored for leas by hundreds of sensors that automatically form a wireless interconnection network and immediately report the detection of any chemical leaks.

Unlike traditional wired system, deployment costs would be minimal. Instead of having to deploy thousands of feet of wire routed through protective conduit, installers simply have to place quarter-sized device, such as the one pictured in Figure 1-1, at each sensing point. The network could be incrementally extended by simply adding more devices-no rework or complex configuration. With the devices presented in this research, the system would be capable of monitoring for anomalies for several years on a single set of batteries.

In addition to drastically reducing the installation costs, wireless sensor networks have the ability to dynamically adapt to changing environments, adaptation mechanisms can respond to changes in network topologies or can cause the network to shift between drastically different modes of operation. For example, the same embedded network performing leak monitoring in a chemical factory might be reconfigured into a network designed to localize the source of a leak and track the diffusion of poisonous gases. The network could then direct workers to the safest path for emergency evacuation.

## II. WIRELESS COVERAGE PROBLEMS

Coverage is the measure of QoS of sensing function and is subject to a wide range of interpretations due to large variety of sensors and applications. Considering the coverage concept, different problems can be formulated, based on the subject to be covered (Area versus discrete points) and on the design choices, such as sensor development method, additional critical

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requirements, sensing and communication radius N. Xu et al. (2004).

A wide classification can be done with respect to the type of algorithm used as well. Centralized versus distributed/localized. We also compare these approaches and algorithm based on their goals, assumption, complexities and usefulness in practical scenarios. Objective of these design choices are either to maximize network lifetime; minimize number of sensors or optimize degree of coverage, and so on a comprehensive study on coverage connectivity research can be found in Akyidiz et al. (2002).

Coverage can be classified of three types based on the subject to be covered. Area coverage, point coverage and barrier coverage. The most studied problem is the area research is going on in both the static and mobile sensor network D. Tian et al. (2002).

The design choices are given bellow:

1. Sensor deployment strategies: deterministic versus random. A deterministic sensor placement may be feasible in friendly and accessible environments. Random sensor distribution is generally considered in military applications and for remote or inhospitable areas.
2. Energy Requirement: In the most typical scenarios, energy requirement is a big factor as sensors are usually limited with respect to its battery life. Several research work has been done on energy efficient coverage.
3. Sensing and communication Radii: Homogeneous/Heterogeneous sensor network is the subject of interest here. While constraints are less in homogeneous sensor network heterogeneous sensor network has a wider scope in applications.

A broader classification of coverage problems can also be done in terms of their goals, assumptions, algorithm complexities and practical applicability. The three categories are

1. Coverage based on the exposure path
2. Coverage based on sensor deployment strategies
3. Miscellaneous strategies

### III. MINIMAL EXPOSURE PATH: WORST CASE COVERAGE

Coverage is a measure of how well a sensing field is covered with sensors.

Informally stated, it can be defined as the expected average ability of observing a target moving in the sensing field. The minimal exposure path provides valuable information about the worst case coverage in sensor networks.

The basis of the proof adopted to compute the exposure path of one sensor lies in the fact that since any point on the dotted curve is closer to the sensor than any point lying on the straight line segment along

the edge of the square; the exposure is more in the former case.

Also, since the length of the dotted curve is longer than the line segment, the dotted curve would induce more exposure with an object travels along it, given that the time duration is the same in both the cases. Furthermore, this method is extended when the sensing region is a convex polygon and the sensor is located at the center of that inscribed circle.

This intuition can further be extended to compute the minimal exposure path under the scenario of many sensors. To simplify, the problem can be transformed from the continuous domain into a tractable discrete domain by using an  $m \times n$  grid. The minimal exposure path is then restricted to straight line segment connecting any two consecutive vertices of a grid square. This approach transforms the grid into an edge weighted graph and computes minimal exposure path using Dijkstras single source shortest path algorithm.

### IV. MAXIMAL EXPOSURE PATH: BEST CASE COVERAGE

A maximal exposure path between two arbitrary points's and t in a sensing field is a path following which the total exposure is maximum. It can be interpreted as a path having the best case coverage. It has been proved by Z. Butler (2004). That finding the maximal exposure path is NP-hard because it is equivalent to finding the longest path in an undirected weighted graph, which is known to be NP-hard. However, there exist several heuristics to achieve near-optimal solutions under the constraints that objects speed, path length, exposure value and times.

### V. MAXIMAL BREACH PATH: WORST CASE COVERAGE

A minimal exposure path is equivalent of finding a worst case coverage path, which provides valuable information about node deployment density in the sensing field. A very similar concept to find out worst case coverage path is the notation of maximal path Meriall (2003).

A maximal breach path through a sensing field starting at s and ending at t is a path, such that for any point p on the path, the distance from p to the closest sensor is maximum. The concept of Voronoi diagram, a well known construct from computational geometry is used to find a maximal breach path in a sensing field.

It is also proved intuitively since by construction, the line segments in a Voronoi diagram maximizes the distance from the closest sites, the maximal breach path must lie along the Voronoi edges. The algorithm then checks the existence of a path from s to t using breadth-first-search (BFS) and uses binary search between the smallest and largest weight in the computed Voronoi graph to find the maximal breach path.

## VI. MAXIMAL SUPPORT PATH: BEST CASE COVERAGE

A maximal Support path through a sensing field starting at  $s$  and ending at  $t$  is a path, such that for any point  $p$  on the path, the distance from  $p$  to the closest sensor is minimized. This is similar to the concept of maximal exposure path. However, the difference lies in the fact that a maximal support path algorithm finds at any given time instant.

Such that the exposure on the path is no less than some particular value which should be maximized. A maximal support path in a sensing field can be found by replacing the Voronoi diagram by its dual, Delaunay triangulation where the edges of the underlying graph are assigned weights equal to the length of the corresponding line segments in the delaunay triangulation Z. Butler (2004). This ends our brief discussion on coverage problems based on exposure path in WSNs. Next, we discuss different deployment strategies which impact coverage in WSNs.

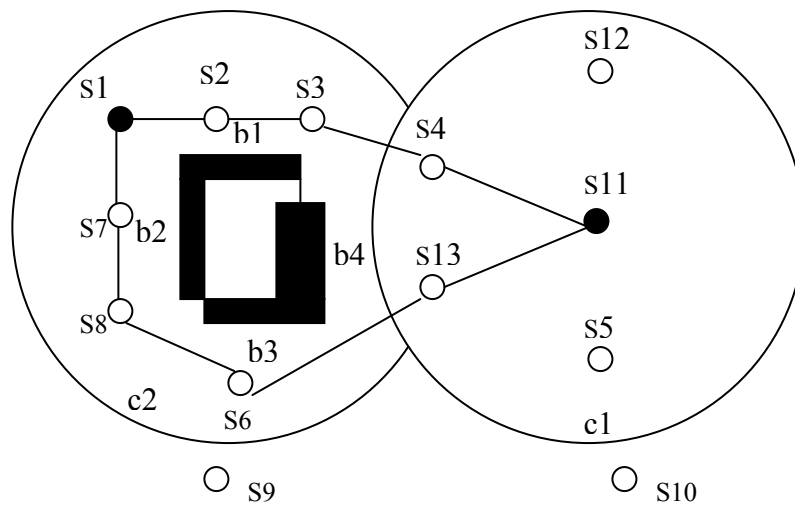
## VII. COVERAGE BASED ON SENSOR DEPLOYMENT STRATEGIES

The second approach to the coverage problem is to find sensor deployment strategies that would maximize the coverage as well as maintain a globally

connected network graph. Several deployment strategies have been studied for achieving an optimal sensor network architecture that would minimize cost, provide high sensing coverage, and be resilient to random node failure etc. the most usual deployment strategy of sensor nodes are random deployment.

However, random placement does not guarantee full coverage because it is stochastic in nature, hence often resulting in accumulation of nodes at certain areas in the sensing field whereas leaving other areas deprived of nodes. Keeping this in mind, some of the deployment algorithms try to find new optimal sensor locations after an initial random placement and moves the sensors to those locations, achieving maximum coverage. These algorithms are applicable to only mobile sensor networks.

Research has also been conducted in mixed sensor networks, where some of the nodes are mobile and some are static; and approaches are proposed to detect coverage holes after an initial deployment and trying to heal or eliminate those holes by moving sensors. It should be noted that an optimal deployment strategy should result not only in a configuration that would provide sufficient coverage, but also satisfy certain constraints such as node connectivity and network connectivity [40].



Sensor Field with Four blocks  $b_1, b_2, \dots, b_4$  and sensors

## VIII. Algorithm: Find Best Coverage( $S:s:T$ )

1. Find closest sensor node of the starting point  $s$  if itself is not a sensor node. Assume  $S_7$  is the closest sensor node. Similarly, find the closest sensor node  $S_{13}$  of the ending  $t$ .
2. Each sensor node  $S$  locally constructs all edges  $S_v$  of the relative neighborhood graph broadcasts its location information and listen to the broadcasting by its neighbors. Thus, after this step, we assume

that each node  $S$  has the location information of  $NI(S)$ .

3. Assign each constructed edge  $S_v$  with weight 1.
4. Run a distributed shortest path algorithm to compute the shortest path Connecting  $S_s$  and  $S_t$ . Here, the weight of a path is the maximum weight of all of its edges.

Here a path is the shortest path if it has the minimum weight among all paths connecting  $S_s$  and  $S_t$ . the Bellman-Ford algorithm M. Bauer (2004) can be modified to solve this shortest path problem.



## IX. Conclusion

In this thesis we present an overview of coverage and the coverage related problems in the presence of block. We also present an algorithm to overcome this problem by using approximation algorithm called CIB coverage in block algorithm. The upcoming technological advances will most likely be applied to decreasing the power consumption of the device. In trun, this will enable a reduction of physical size of the energy storage required for any given application. as for tighter levels of integration, the cost/size point represented by the spec platform has reached the point of diminishing returns. Further reduction in the physical size of the radio, processing, and storage is no longer necessary. Only a select few application have the need for a device that is smaller that 2.5 mm × 2.5 mm. However, all application scenarios can benefit from reduced power consumption which is translated into longer network lifetime and / or increased sample rate.

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# ESAHR: Energy Efficient Swarm Adaptive Hybrid Routing Topology for Mobile Ad hoc Networks

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**Abstract** - Ad hoc networks consist of independent self structured nodes. Nodes use a wireless medium for exchange their message or data, therefore two nodes can converse directly if and only if they are within each other's broadcast range. Swarm intelligence submits to complex behaviors that occur from very effortless individual activities and exchanges, which is frequently experienced in nature, especially amongst social insects such as ants. Although each individual (an ant) has little intelligence and simply follows basic rules using local information gained from the surroundings, for instance ant's pheromone track arranging and following activities, globally optimized activities, such as discovering a shortest route, appear when they work together as a group. In this regard in our earlier work we proposed a biologically inspired metaphor based routing in mobile ad hoc networks that referred as Swarm Adaptive Hybrid Routing (SAHR). . With the motivation gained from SAHR, here in this paper we propose a energy efficient swarm adaptive hybrid routing topology (ESAHR). The goal is to improve transmission performance along with energy conservation that used for packet transmission In this paper we use our earlier proposed algorithm that inspired from Swarm Intelligence to obtain these characteristics. In an extensive set of simulation tests, we evaluate our routing algorithm with state-of-the-art algorithm, and demonstrate that it gets better performance over a wide range of diverse scenarios and for a number of different assessment measures. In particular, we show that it scales better in energy conservation with the number of nodes in the network.

**Keywords** : *Manet, Swarm intelligence, hybrid routing, unicast routing, ACO.*

**GJCST-E Classification** : *B.4.3*



ESAHR ENERGY EFFICIENT SWARM ADAPTIVE HYBRID ROUTING TOPOLOGY FOR MOBILE AD HOC NETWORKS

*Strictly as per the compliance and regulations of:*



RESEARCH | DIVERSITY | ETHICS

# ESAHR: Energy Efficient Swarm Adaptive Hybrid Routing Topology for Mobile Ad hoc Networks

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**Abstract** - Ad hoc networks consist of independent self structured nodes. Nodes use a wireless medium for exchange their message or data, therefore two nodes can converse directly if and only if they are within each other's broadcast range. Swarm intelligence submits to complex behaviors that occur from very effortless individual activities and exchanges, which is frequently experienced in nature, especially amongst social insects such as ants. Although each individual (an ant) has little intelligence and simply follows basic rules using local information gained from the surroundings, for instance ant's pheromone track arranging and following activities, globally optimized activities, such as discovering a shortest route, appear when they work together as a group. In this regard in our earlier work we proposed a biologically inspired metaphor based routing in mobile ad hoc networks that referred as Swarm Adaptive Hybrid Routing (SAHR). With the motivation gained from SAHR, here in this paper we propose a energy efficient swarm adaptive hybrid routing topology (ESAHR). The goal is to improve transmission performance along with energy conservation that used for packet transmission. In this paper we use our earlier proposed algorithm that inspired from Swarm Intelligence to obtain these characteristics. In an extensive set of simulation tests, we evaluate our routing algorithm with state-of-the-art algorithm, and demonstrate that it gets better performance over a wide range of diverse scenarios and for a number of different assessment measures. In particular, we show that it scales better in energy conservation with the number of nodes in the network.

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## I. INTRODUCTION

In disparity to merely establishing accurate and efficient routes among pair of nodes, one significant goal of a routing topology is to remain the network functioning as long as potential. This objective can be consummate by reducing mobile nodes energy not only through active communication but also when they are not participating. Communication energy control and load allocation are two approaches to reduce the energy levels of active communication, and sleep/energy-down mode is used to reduce energy through inactivity.

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Wireless ad hoc networks typically consist of mobile battery functioned computing devices that correspond over the wireless medium. While the dispensation ability and the memory space of computing devices augment at a very rapid speed, the battery method wraps distant behind. Therefore, it is significant to obtain energy preservation schemes to augment the device and network process time.

In wireless networks, the broadcasted signal is assuaged at the speed of  $1/d^n$ , where  $d$  is the distance among sender and receiver and  $n$  is the route loss exponent with approximate value between 2 and 6 depending on the equipped environment. As an alternative of using the maximum energy for transmissions all the time, with energy control, a sender can regulate the communication energy according to  $d$ . Though, link level energy control cannot make sure that the end-to-end energy utilization from a source to a destination is minimal. To conserve energy, many energy efficient routing topologies have been projected [1, 2, 3, 4, 5, 6, 7, 8, 9]. These topologies can be usually classified into two categories: Minimal Energy usage routing topologies [1, 2, 3, 4, 5, 6] and Utmost Network Lifespan routing topologies [8, 9].

In existing minimal energy routing topologies, signaling packets are often transmitted at the maximum energy to reduce the hidden terminal problem as a result of using asymmetric transmission energy from different adjacent nodes. The signaling packet effects by more collisions, for instance the RTS packet in 802.11, would use noteworthy amount of energy. Without taking into consideration the energy utilized for transmitting, the route exposed could utilize much more energy than a route selected based on a more precise energy utilization model. In addition, the majority of literature works paying attention only on the direction of new hop level transmission cost is resultant, the traditional shortest route routing topologies, for instance AODV (Ad hoc On Demand Distance Vector) and DSR (Dynamic Source Routing) topologies, are customized to search for the minimum cost route. Though, such straightforward customization would lead to numerous problematic issues. Foremost, the routing overhead in route detection phase is excessive, which not only utilizes a significant amount of energy but also shows the way to a long route establishment delay impediment. Second, the route maintenance plan used in conservative

shortest route topology is not suitable for maintaining energy efficient route in a mobile environment.

In this paper, we first present a comprehensive argument on the problems in conventional energy efficient routing topologies. We then derive a new hop level transmission cost model to account for energy utilization due to signaling packets at MAC layer, and make available the schemes for approximation the parameters necessary for calculating the hop level transmission cost. Based on the new energy utilization model, we extend our earlier work Swarm Adaptive Hybrid Routing topology [14] as Energy Efficient Swarm Adaptive Hybrid Routing topology for energy conserved data transmission along the route discovered by swarm adaptive hybrid routing topology [14].

This paper discussing the related work in section II that followed by the exploration of the proposed energy efficient swarm adaptive hybrid routing topology in section III. Section IV elaborates the considered basic routing topology SAHR and section V explores simulations and results analysis, which followed by the conclusion of the proposal and experiments.

## II. RELATED WORK

There are numerous obtainable routing topologies for wireless ad hoc networks. In general, these topologies can be categorized as proactive, on-demand, and hybrid. In proactive routing topologies, all nodes need to advertise the routing information periodically to keep an up to date view of the network topology. Different from table driven routing topologies, on-demand routing topologies create a transmission route only when required by the source node. Hybrid topologies combine both approaches. For example, in Zone level Routing Topology (ZRP), proactive routing scheme is used for intra-zone level routing and on-demand routing scheme is used for inter-zone level routing. Most of energy efficient schemes proposed in the literature modified on-demand routing topologies such as AODV [16] or DSR [17] to build energy efficient route since the routing overhead is very high in proactive routing topologies [2]. In on-demand routing topologies such as AODV, a node will initiate a route detection process if it needs to find a route to a target node. It transmits the route request packet and waits for the reply from the target node.

The adjacent nodes that receive these route request packet will retransmit it, and so on. To decrease the routing overhead, the intermediary nodes will only retransmit the first conventional route request packet and discard the subsequent duplicate ones. In addition, the target node only replies to the first route request packet. It is obvious that the overhead for these on demand routing topologies is  $O(n)$ , where 'n' is the number of nodes belongs to the network considered.

Route detection in energy efficient routing topologies is however fairly dissimilar. The intermediary nodes could not simply discard the duplicate route request packets now as such packets may come from more energy efficient routes. That is, the intermediate nodes need to process and retransmit the duplicate route request packets if they come from a more energy efficient route. Consequently, the nodes may require transmitting the same route request packet numerous times.

In the context of the routing topology SAHR [14], several successful routing algorithms have been proposed taking inspiration from ant colony behavior and the related framework of Ant Colony Optimization (ACO) [8A]. Examples of ACO routing algorithms are AntNet [6A] and ABC [13].

The ACO routing algorithms mentioned before were developed for wired networks. They work in a dispersed and restricted way, and are capable to study and adjust to transformations in traffic models. However, changes in MANETs are much more drastic: in addition to disparities in traffic, both topology and number of nodes can change incessantly. Additional complexities are caused by the partial realistic bandwidth of the communal wireless channel, even though the data transmission pace of wireless communication can be fairly high, algorithms in use for MAC, such as IEEE 802.11 DCF [15], create a lot of overhead both in terms of control packets and delay, lessening the effectively available bandwidth. The autonomic control confronts are consequently much bigger, and new designs are essential to assurance even the basic network functions.

## III. ENERGY EFFICIENT SWARM ADAPTIVE HYBRID ROUTING TOPOLOGY FOR MOBILE AD HOC NETWORKS

1. When a route to a target node  $D$  is obligatory, but not known at source node  $S$ ,  $S$  transmits a Rout Trace Swarm Agent **RTSA** to discover a route to  $D$ .
2. When  $D$  receives the **RTSA** from  $S$ , it initiates to transmit **RTSA** as Route Confirmation Swarm Agent **RCSA**, which transmits in backward manner through the route that traced by parent **RTSA**. The **RCSA** updates the routing table and emission table of all the nodes in the route from  $S$  to  $D$ , allowing for data transfer from  $S$  to  $D$ . Here emission table is maintained by each node  $n$  to store emission attribute value  $sav_{ni}$  of its each forwarding neighbor  $ni$ . The emission attribute value is similar to pheromone repository of the biological swarm agent.
3. When a route fall shorts at an intermediate node  $X$  then SAHR reinitiates route detection process.



4. When a route at  $D$  is known to  $S$ , SAHR deterministically chooses the route by opting to best forwarding hop level neighbor  $ni$  based on their hop level delay and number of hops to reach the destination.

#### IV. SWARM ADAPTIVE HYBRID ROUTING TOPOLOGY [14]

SAHR's style is stimulated by Swarm Agent Optimized routing algorithms for wired networks. It uses swarm agents that follow and update emission tables in an indirect agent interaction for the modification of the surroundings learning method. Knowledge packets are routed stochastically consistent with the learned tables. A vital distinction with alternative Swarm Agent Optimized routing algorithms is that SAHR could be a hybrid algorithm, so as to deal higher with the precise challenges of Manet environments. It's reactive within the sense that nodes solely gather routing info for destinations that they're currently communicating with, whereas it's proactive as a result of nodes try and maintain and improve routing info as long as communication goes on. we tend to build a distinction between the trail setup, that is that the reactive mechanism to get initial routing info a couple of destination at the beginning of a session, and route maintenance and improvement, that is that the traditional mode of operation throughout the course of a session to proactively adapt to network changes. The routing info obtained via indirect agent interaction is unfolded between the nodes of the Manet in hop level neighbor info exchange method to supply secondary steerage for the swarm agents. Within the following we offer a broaden description of the SAHR.

SAHR's design is inspired by swarm agent optimized routing algorithms for wired networks. It uses swarm agents which follow and update emission tables in an indirect agent interaction about the modification of the environment learning process. Data packets are routed orderly in accord to the learned tables. An important difference with other Swarm Agent Optimized routing algorithms is that SAHR is a hybrid algorithm, in the process of dealing better with the specific MANET confronts. It is on-demand in the sense that nodes only collect routing information for targets which they are at present corresponding with, while it is proactive because nodes try to maintain and improve routing information as long as communication is going on. We make a distinction between the route setup, which is the on demand mechanism to acquire initial routing information about a destination at the start of a session, and route maintenance and perfection, which is the usual mode of process through the course of a session to proactively acclimatize to network changes. The routing information obtained via indirect agent interaction learning is spread between the nodes of the

MANET in a hop level neighbor information exchange process to provide secondary guidance for the swarm agents. In the following we provide a concise description of each of these components.

##### a) Pheromone Indicator for ESAHR

Routes are implicitly outlined by the emission tables that are kept regionally at every node. An entry  $g_{ni}$  of the emission table  $ST_i$  at node  $i$  that consider as pheromone indicates about the goodness of the routing from node  $i$  to via immediate node  $ni$  contains a price indicating the estimated goodness of going from  $i$  over neighbor  $ni$  to reach destination  $d$ . This goodness is derived from the combination of route end-to-end delay and range of hops. These are commonly used quality measures in Manets. Combining the number of hops with end-to-end delay between immediate node  $ni$  to current node  $i$  and destination node  $d$  is a way to swish out presumably giant oscillations within the time estimates gathered by the swarm agents. Since SAHR solely maintains info regarding destinations that are active during a communication session, and due to continuous change at neighbor nodes, the filling of the emission tables is dynamic.

##### b) Route Detection in ESAHR

The source node  $s$  determines the route to node  $d$  via transmitting Route Trace Swarm Agent **RTSA**. At each neighbor hop that received **RTSA**, transmits the same to their neighbor hops. This process is recursive for each **RTSA** till it received by destination node  $d$ . Upon receiving the **RTSA**, the destination node  $d$  initiates to transmit Routing-route Confirmation Swarm Agent **RCSA** that derived from **RTSA**. **RCSA** Transmits in backward manner through the route that traced by parent **RTSA**. Upon reaching each node  $i$  in the routing route, **RCSA** updates pheromone indicator value  $g_{ni}$  of relay hop node  $ni$  of the current node  $i$  in the routing route opted by **RCSA**. The process of updating the pheromone indicator value is as follows: During the transmission of swarm-agent **RCSA**, it collects the time  $t_{ni \rightarrow i}$  taken to reach each node  $i$  from relay hop node  $ni$  the '**RCSA**' is coming from. The estimated time  $t_{i \rightarrow d}$  to transmit a data packet from node  $i$  to destination node  $d$  via  $\{ni, ni+1, ni+2...ni+n\}$  is measured using equation (1).

$$t_{i \rightarrow d}^{ni} = t_{(ni+n) \rightarrow d} + \sum_{k=n}^1 t_{(ni+k-1) \rightarrow (ni+k)} \quad (1)$$

And then pheromone indicator value will be measured using equation (2) and (3) that follows



$$\left(t_{i \rightarrow d}^{ni}\right)' = \left[t_{i \rightarrow d}^{ni}\right]^{-1} * 100 \quad (2)$$

$$g_{ni} = \frac{\left(t_{i \rightarrow d}^{ni}\right)'}{hc_{i \rightarrow d}^{ni}} \quad (3)$$

Here in equation (3),  $hc_{i \rightarrow d}^{ni}$  indicates the hop count in route from current node  $i$  to destination node  $d$  via relay hop node  $ni$ .

The inverse value of the estimated time  $t_{i \rightarrow d}^{ni}$  for a data packet to travel from node  $i$  to destination node  $d$  indicates the optimality of the route between nodes  $i$  to destination node  $d$  via relay node  $ni$ . Hence the equation (2) is significant.

Upon receiving swarm agent **RCSA**, the source node  $s$  also updates its emission table with pheromone indicator value  $g_{ni}$  of each neighbor hop  $ni$  the **RCSA** coming from.

#### c) Energy efficient Data transmission and route maintenance in ESAHR

The routing-route maintenance will be carried out in proactive manner and will be initiated at destination node  $d$ . The data transmission and route maintenance strategies explored in following subsections.

##### i. Data Transmission with minimal Energy Usage

In the process of transmitting data, source and hop level node selects the target neighbor relay hop dynamically. Initially source node finds best neighbor  $ni$  based on pheromone indicator value of the nodes registered in its emission table. Opting to a neighbor relay hop  $ni$  with best pheromone indicator value  $g_{ni}$ , transmits data packet to selected neighbor relay hop  $ni$ . Upon receiving the data packet the neighbor relay hop registers the sender's information in routing cache. The strategy of selecting neighbor relay hop dynamically and transmitting data packet is recursive at each neighbor hop relay node. This process will be halted once the data packet received the destination node  $d$ . And as an extension to this process a energy conservation mechanism introduced to minimize the energy usage in data transmission that described in section ii that follows.

##### ii. Minimal Energy Usage for data transmission in ESAHR

The nodes are having limited energy and storage capacity, Hence the Energy efficient Swarm Adaptive Hybrid Routing topology has been proposed that saves energy resources. Here in this proposed ESAHR model the **RTS** packet takes the energy used

for communication by the source node of that **RTS**. Then the target node of that **RTS** finds the state of the signal that used to send out **RTS**.

$$SS_r = SS_s (\alpha / 4\pi d)^2 S_T S_R$$

Here  $\alpha$  is the wavelength of the signal to be carried,  $d$  is the distance travelled by **RTS** between source and target nodes.  $S_T$  is the single plane uniform radio wave transmission threshold of source node antennas and  $S_R$  is the single plane uniform radio wave receiving threshold of target node antennas. ' $SS_s$ ' is the actual state of the transmission signal energy at the source node  $s$ . And  $SS_r$  is the state of the signal energy that found at target node  $r$ , which used to transmit **RTS**.

Then the loss state of signal  $SS_l$  during routing can be found at target node  $r$  by using the following equation.

$$SS_l = SS_r - SS_s$$

And then this  $SS_l$  can be used to find minimal signal state  $SS_m$  required at the source node, the equation is as follows

$$SS_m = mh \times (SS_l + RSS_m)$$

Here in the above equation

The ' $SS_m$ ' indicates minimal signal state required at the source node  $s$

The ' $mh$ ' is the marginal hike threshold that is used to normalize  $SS_m$  to handle the inference issues on the target node side.

The ' $RSS_m$ ' indicates the minimal signal state required at receiving node side to detect the appropriate signal.

There are a set of topologies available for energy control in mobile ad-hoc networks based on the common energy approach [10]. These topologies are complex and have been analyzed that the variable range transmission energy is a better approach than the general energy.

The proposed ESAHR is capable to conserve the energy even to transmit **RTS/CTS** packets, which is based on the received signal condition. When a source node needs to transmit data, it initiates the optimal routing strategy such as AODV and then transmits the **RREQ** packet to the hop level nodes and the **RREP** packet is received from the intermediate nodes via the shortest route and then enters it in their routing table about the next hop to which the anon data packets are desired to be advanced.

For energy preservation, the RREP packet is recognized by an identifier (id) at the MAC layer and its signal state information is attained from the physical layer. Upon receiving the **RREP** packet by a node ' $r$ ' from a node ' $s$ ', the node ' $r$ ' computes loss state of the signal  $SS_l$  during the RREP transmission from node ' $s$ ' to ' $r$ ' and minimal signal state  $SS_m$  required at node ' $s$ '. And then node ' $r$ ' stores minimal signal state required for the node ' $s$ ' in its routing table.

The process of energy conservation during data transmission in proposed ESAHR as follows:

The source node ' $s$ ', while sending **RTS** to its next hop level node  $r$  of the routing route, also sends the  $SS_m(r)$  stored in its routing table. Here  $SS_m(r)$  is the minimal signal state required for  $r$ , which is measured and stored in the routing table of node  $s$  during route detection. The source node  $s$  also includes  $SS_m(s)$  as an extra field in the RTS packet. Upon receiving the **RTS**, the target node  $r$  tunes its transmission energy and replies back with '**CTS**' packet. Upon receiving the **CTS** the source node  $s$  sends the data with the requisite transmission energy informed by the target node  $r$  through '**CTS**'.

#### iii. Routing Route maintenance

Upon receiving a packet  $dp_i$ , the destination node  $d$  verifies the time  $t(dp_i)$  taken by  $dp_i$  to travel from source node  $s$  to destination node  $d$  and then measures the end to end delay for data packet  $dp_i$ . If end to end delay of  $dp_i$  is exceeding the delay threshold  $\tau$  then it initiates a swarm agent **RCSA** and transmits towards source node that opts to the route accessed by data packet  $dp_i$ . Hence the '**RCSA**' performs the process of updating pheromone indicator value  $g_{ni}$  at each hop level relay node in the route. This process explored in equations (1), (2) and (3).

#### iv. Handling link failures

The destination node  $d$  initiates swarm agents **RCSA** to each neighbor relay hop nodes in fixed time intervals. Hence the pheromone indicator values in emission table of each node will be updated in fixed time interval  $\zeta$ .

The pheromone indicator value of any neighbor relay hop  $ni$  in emission table of any node  $i$  is not valid if time since last update of  $g_{ni}$  is greater than time interval  $\zeta$ . This indicates the link failure between node  $i$  and destination node  $d$ .

## V. EXPERIMENTAL RESULTS

We have simulated ESAHR, SAHR, as well as basic AODV topologies in NS2. The position per hop transmission distance is 250m. For energy maintenance function, many smaller hop level nodes are taken. Energy management is used in all three topologies, including normal AODV topology, in which a transmitter adjusts the transmission energy based on its actual distance to the next hop level receiver. The network area in the simulation is fixed to 1200(m) X 1200(m) and the nodes are arbitrarily dispersed in the network. The available transmission energy levels are 1; 5; 10; 15; 20; 25; 30; 35mW. The Pm is set to 35 mW. The session arrival rate follows Poisson distribution and the session interval follows Exponential allocation. The application topology is CBR (Constant Bit Rate) and the source and target pairs are arbitrarily selected. The mobility follows customized random waypoint model [18] with pause time of thirty seconds. For each CBR session, 50 packets are sent for each second. The rate of route loss and collision are projected using method described in [12]. The detection rate, which can be described as filter memory [11], is fixed to nearly 1. A simulation result was gained by averaging over 25 executions with dissimilar seeds.

We consider that there is no energy saving approach for the nodes, and therefore, a node will use energy in monitoring the channel even if it doesn't receive a packet. A node also utilizes energy when overhearing packet transmissions. Therefore, the receiving energy cannot be dynamically controlled. In the simulations, we thus disregard the receiving energy and focus only on the comparison of transmission energy. We first evaluate the accuracy of the proposed cost model, we then study the performance of route detection for each topology, and finally we consider energy utilization as well as RTS retransmissions in both static and mobile environment.

We compared the energy utilization and the average number of RTS retransmissions of the ESAHR, SAHR and basic AODV topologies by varying the following parameters: node count, average size of the data transmission packets, and advent ratio of the connection. The simulation time for each topology is 5 hours. We monitored the total energy utilization of all the packets delivered at target node, the count of delivered packets at target nodes, and the count of retransmissions RTS required for each execution of the simulation. The couple of evaluation metrics that used to evaluate the topologies are:

**Energy Utilization per Packet:** It is defined by the total energy utilization divided by the total number of packets delivered. This metric indicates the energy efficiency for each topology.

**Average RTS Retransmissions required for each Data Packet:** It is defined by the total number of RTS

retransmissions divided by the total number of packets delivered. The RTS packet is transmitted at the utmost energy usage level and the packet size is very little. The majority of RTS retransmissions are due to collisions, together with the collisions of both RTS messages and data packets. Hence, this metric can indicate the pace of the collision for each topology. Higher collision rate will cause more energy utilization, higher end-to-end delay, and lower throughput.

The simulation results are shown in Fig. 1 and 2. According to these results, ESAHR topology performs the best in terms of Energy Utilization per Packet as well as Average RTS Retransmission per Data Packet, followed by SAHR topology and AODV.

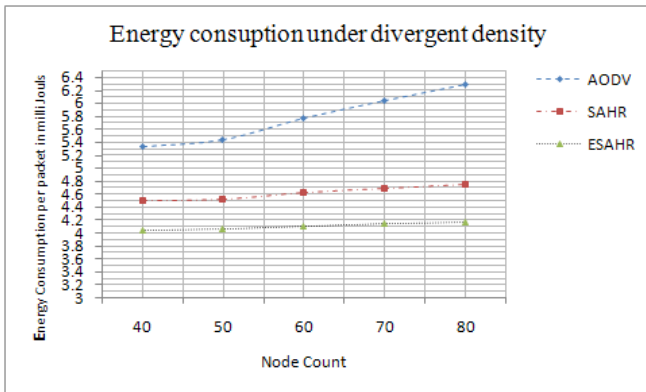


Fig. 1 : Energy Utilization ratio between ESAHR, SAHR and AODV

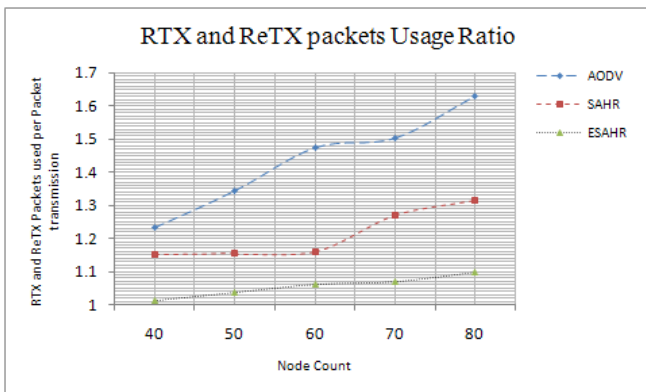


Fig. 2 : RTX and ReTX packets usage Ratio comparison between AODV, SAHR and ESAHR

## VI. CONCLUSION

In this paper we have described ESAHR that is an extension to our earlier routing topology SAHR[14], an Energy efficient Swarm Adaptive hybrid routing (ESAHR) topology for MANETs. The algorithm combines reactive and proactive behavior with swarm intelligence adaptation to deal with the routing challenges of MANETs in an efficient way. This also concern about energy conservation during packet transmission. An efficient hop level transmission cost model to more accurately track the energy utilization due to various

factors was explored for packet transmission through the route discovered and maintained under SAHR topology. Our performance studies show that ESAHR topology reduces about 40% usage of energy used during packet transmission, and is highly adaptive to the environment change. In future this topology can be equipped with route overhead endurance mechanism.

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# Authorised Secure Host Communication under Data Provenance Verification- A Signcryption Based Contract Signing Protocol

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**Abstract** - The wide qualities of distributed (ex: P2P networks) network has given us many advantages and threats for enhancement of distributed computing. The best way to reduce threats is adding a reputation-based globally trusted model. Many present trust models are failing to restrain effectively some behaviors like collusive attacks, but pay no heed towards the security of this mechanism.

*GJCST-E Classification : E.3*



AUTHORISED SECURE HOST COMMUNICATION UNDER DATA PROVENANCE VERIFICATION- A SIGNCRYPTION BASED CONTRACT SIGNING PROTOCOL

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# Authorised Secure Host Communication under Data Provenance Verification- A Signcryption Based Contract Signing Protocol

Bolladi Swathi<sup>α</sup> & P.Vasanth Sena<sup>σ</sup>

**Abstract** - The wide qualities of distributed (ex: P2P networks) network has given us many advantages and threats for enhancement of distributed computing. The best way to reduce threats is adding a reputation-based globally trusted model. Many present trust models are failing to restrain effectively some behaviors like collusive attacks, but pay no heed towards the security of this mechanism.

## I. Introduction

Of late, distributed computing has become popular and well recognized in a wide range of applications, like file-sharing, digital content delivery, and distributed Grid computing [1]. But the fact remains that, peer anonymity and autonomy make distributed networks easy towards attacks by any peer who is not rust worthy. The recent works [2-5] are a benchmark to the fact that the trust theories in social networks construct well recognized trust models, to find a solution for these kinds of behaviors.

The present reputation-based trust model designs trusted rank of a peer based on its past transactions, and it's similar to the peer with full trust value is offered the role of the service provider. This method has some advantages on any malicious behaviors to a certain extent, but has a meager effect when it comes to complex attacks and when disturbances are created on these reputation systems, like collusions. The researches now a day focus on the design and working of the trust system in all sensible arenas, and barely care concerning the security difficulty it faces which can damage the tag "node consistency handling". The security of node reliability handling is the most important element which assures a safe working of the trust management system (TMS). Thus, it is vital to develop and discuss about the security mechanism of the TMS.

Dealing by means of these research issues, we project node reliability based distributed trust model with the security mechanism that we refer as the secure node reliability information management (SNRIM), for

distributed networks, which would scales better over node reliability information management(NRIM).

## II. Related work

This sector gives a wide review of some of the present distributed node reliability systems, concentrating on problems like storage and veracity. We would like to at first give an outline of the node reliability systems. Kevin A. Burton designed an open privacy distributed node reliability system [5] on p2p, which hails from the distributed trust model which brought to us the idea of node reliability network, which is made up of identities and certificates. Therefore, the certainty of the identities is appreciated from a visible sub-graph of the reputable network. P2PREP [6], which is a node reliability sharing protocol designed for Gnutella, where every peer keeps track and shares the node reliability of their peers. Reputation sharing is made by distributed polling protocol. Service requesters use this trust by polling peers. Karl Aberer et.al. [7] Made a trust managing system on the distributed system which combines the trust and data management to construct a complete distributed architecture for information systems. The node reliabilities here are expressed as complaints; higher the complaints, less trustworthy it is. After every transaction, if there is dissatisfaction, a peer files a complaint stating the problem. To examine the node reliability of a peer involves searches for complaints about the peer. Kamvar et.al [8] proposed a node reliability management system, for distributed file sharing systems such as Gnutella fighting against the spread of inauthentic file. Here, every peer has a global node reliability that shows experiences of every peer with it. Sit and Morris [9] gave an idea for security of p2p networks. Their model permits nodes to make packets with arbitrary material, but lets the nodes not to intercept arbitrary traffic. They gave taxonomy of all varied attacks and at the routing layer, they find a node lookup, routing table preservation, division the network and virtualization as threat to security. They deal also with multilevel protocols, like file storage, where nodes need not have the necessary invariants, like storage replication. They work also on denial-of-service attacks, and rapidly joining and leaving the network, or arranging for various nodes which sends bulk volumes of data to overload a

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victim's network connection (i.e., distributed denial of service attacks). Dingleline et al. [10] and Douceur [11] work on address spoofing assaults as well. Having several potentially hazardous nodes in the system and with no trusted central head which certifies node identities and become complex to know whether you can trust the claimed identity of somebody to an unknown. Bellovin [12] finds many problems with Napster and Gnutella. He discusses how complex it is to extent the use of Napster and Gnutella use via firewalls, and the ways they pass information that users feel is personal, like the search queries given. Bellovin researches also on Gnutella's "push" feature, which functions on firewalls, useful for denial of service attacks. He feels Napster's central architecture more safe against these kind attacks, even if it needs users to trust the central server. It is to be renowned that a substitute reply for secure routing table maintenance and forwarding that we denied. This answer exchanges every node by a bunch of replicas as told by Lynch et al. [13]. The replicas are run using a state machine replication algorithm like BFT [14] that can sustain faults like Byzantine. BFT can replicate arbitrary state machines and, therefore, it can look like Pastry's routing table maintenance and forwarding protocols. Here, we look into Reputation Systems for distributed networks—highly useful design which protects the distributed network without a central component, and amplifies all the advantages of the distributed network.

### III. Node reliability Systems

A vital corollary of a good node reliability management is the online auction system eBay [9]. Here, buyers and sellers rate each other post transaction, and the final node reliability of a contestant is the ratings he has over the last 6 months. This system depends on a central system to store and manage these ratings.

In varied areas nodes rate each other post transaction, like in eBay system. Like, every time peer  $i$  gets a file from peer  $j$ , it rates the transaction as positive ( $tr(i, j) = 1$ ) or negative ( $tr(i, j) = -1$ ). Peer  $i$  can rate a download as negative, if he finds the file inauthentic or tampered with, or if interrupted. Like in the eBay approach, we may possibly characterize a local faith value  $s_{ij}$  as the sum of the ratings of the individual transactions that node  $i$  has downloaded from node  $j$ :

$$s_{ij} = ptr_{ij}.$$

Similarly, every peer  $i$  can store many transactions it has had with node  $j$ ,  $sat(i, j)$  and the number of intolerable transactions it has had with node  $j$ ,  $unsat(i, j)$ . Then,  $s_{ij}$  is defined:

$$s_{ij} = sat(i, j) - unsat(i, j) \quad (1)$$

Previous work in distributed node reliability systems [6, 1] are based on same notions of local trust values. The obstacle in an environment is how to deal with the local trust values  $s_{ij}$  without a central storage and management. Every previous system named above finds this problem; every system proposed has a couple of negatives. It mostly averages the ratings of some nodes and has no wide view about a peer's node reliability, or it averages the ratings of the nodes and congests the network with system messages questioning for every peer's local trust values for each query.

#### a) Threat Model

A Gnutella-like network has a power-law topology and helps Insert and Search techniques. The nodes have a predefined Join & Leave protocols. The nodes are connected with a communication channel which is not secure. As the nodes have opposing interests, a motivation is required to decrease leechers. Leechers are the ones who gain benefit from the system without giving anything to the system. The rogue nodes send malware in the network. Finally, nodes judge the quality before making Go/No-Go in every transaction and develop trust relationships mutually.

A good node reliability system gives the way to achieve the target. Any node reliability system is open to ballot stuffing and bad mouthing as told in [18]. A poor node reliability system naturally gives problems that exploit the attackers. Peers should have unique way to handle to which their node reliabilities are tagged. If they are absent in trusted central agency, an attacker gathers infinite identities and gives recommendations to itself. A node can alter the reliability data in the network to uplift its node reliability and there are problems that are in the picture based on how a given node reliability system is made. We discuss those problems and their mitigation in the sections where the design decision is made.

#### b) Self-Certification

To participate in the node reliability system, a node should have handled. The reliability of a node is represented with handle. This handle is the "identity" of the node even if does not "discover" a node, i.e., it may not lead to the real-life identity of the peer. A node gets advices for every transaction, and all advices are stored together for calculation of the reliability of a node.

In a central system, the head gives these identities. In a distributed node reliability system, self-certification [33] divides the trusted entity among the nodes and gives their own identities. Every node has its own CA that gives the identity certificate(s) to the peer. All the certificates used here are same to SDSI certificates [6]. The name of a node is with its identity and the node reliability of a CA is the node reliability.

Self-certification obviates the central trusted entity for giving identities in a central system. Peers

having self-certified identities are pseudonymous in the system as there isn't a way to map the identity of a node in the system to its real-life. Though anonymity or at least pseudonymity is required in distributed networks, in a node reliability system it is a double edge sword. If there is no mapping between multiple identities and the owner (peer), the system is open to Sybil attack or Liar farms.

A node uses self-certification generating many identities and raises the node reliability of identities doing false transactions. The malicious node need not collude with distinct nodes to build its node reliability, but should generate a set of identities. The set of identities managed by one node is called an identity farm. The identities issuing a false recommendation are called a liar farm. These attacks are of the class of attacks named Sybil attacks. A node having an identity farm is as powerful subverting a node reliability system as a node colluded with many of other peers.

An identity farm is countered if, a node is not allowed to one identity or all the identities of a node are sent back the peer. A node can be stopped to one identity by mapping its identity to its real-life identity and leaving anonymity, or by making the identity generation resource high that the node cannot generate more identities. Identity generated is made resource intensive by traditional micro-payment method, although the resource restrictions have a varied impact based on every peer's resourcefulness.

In self-certification, we have a combination of approaches. Every node CA gives many identities. The advices received for a peer's identity from identities of peers, signed by the other peer's CA(s), are recognized as signed by the CA, and are made to counter the liar farms. In every transaction, the requester averages all the advices of the provider by CAs of the provider's last advisors. Hence, all the past advices owned by the provider are but they get averaged. Finally, it sums up the averages of each CA calculating the node reliability of the provider identity.

Hence, a peer should not use its own identities (all generated by the same CA) to advice its other identities.

A determined peer can begin many CAs and give groups of identities. In order to oppose a rogue node with multiple CAs, the nodes are made to batches on various grounds like a node can't be a part of many groups. For example, a distributed network in a city ensures the nodes by their zip codes. Every node gets its group certificate from the required head and attaches it to its CA. The certificate of a group head is publicly used by any node inside or outside the group. The node sends its credentials to the group and the head checks and signs the group certificate.

Unlike the traditional CA or distributed CA ways, grouping of nodes has the anonymity of the peers; when grouped with self-certification it curtails the happening of

a Sybil attack. In opposition to the traditional CA, neither the group head nor the transacting nodes establish the identity of the peer. The certificate revocations are not necessary in the group-based way as the group head vouches for the real-life of the peer, unlike the traditional certificate-based approaches where many certificate attributes are attested by the head and need revocation. If a good identity is adjusted, its misuses are self destructive as its node reliability will go down if misused.

The node is named P while the head is denoted by A. Here  $P \rightarrow A: X$  represents that the node (P) sends a message X to the head (A), here  $P_{k_2}$  stands for the private key of P and  $P_{k_1}$  represents the public key of the node  $P.E_k(\tau)$  represents encryption of the phrase ( $\tau$ ) with K, while  $E_{B_k}(X)$  represents blinding phrase X with key K.

1.  $P \rightarrow A: B1 = \{E_{B_{ka}}(I_{Alice_r})\}, I_{Alice}$  The peer Alice gives a BLINDING KEY, K and identity for herself ( $I_{Alice_r}$ ). Alice cannot be recognized from her identity ( $I_{Alice_r}$ ). She also blinds her identity ( $I_{Alice_r}$ ) with the blind key Ka. B1 stands for the blind identity. Alice passes B1 to the head with her real identity that approves her membership to a group.
2.  $A \rightarrow P: B2 = E_{P_{AuthorityK_2}} \{B1 = E_{B_{ka}}(I_{Alice_r})\}, I_{Alice}$  The head attests the blinded identity, B1 and sends it (B2) back to the peer.
3.  $E_{P_{AuthorityK_2}} \{I_{Alice_r}\} = E_{B_{ka}} \{B2\}$  The peer unblinds the signed identity and extracts the identity authorized by the head  $E_{P_{AuthorityK_2}} \{I_{Alice_r}\}$ .

The logic in the group-based way is that in a distributed network, nodes are interested in the ranks of providers than only the value of the node reliabilities. The simulations tell that this way varies the name of nodes but it having least effect on the relative ranks of the peers. This approach is from the Google page rank idea in which the pages in proximity of other don't give the page rank of the target page in the pages at a distance [34]. The relative ranks don't object the nodes from adjusting thresholds. The thresholds depend on ranks. Adjusting the thresholds for absolute values are have a limited utility. Google has ranks instead of links pointing to/from pages. It is clear from the Google corollary that rank-based mechanisms can be measured. Debates between there might be some systems needing absolute values still take place. This paper is not into that, as use of absolute values is more complex and is specific information that is not a part of our discussion.

It is opposed and supported that this way is unjustified to nodes whose authentic advice are from



nodes that are a part of a large group. We support the argument and our implementations display that the relative ranks of the providers change the least. Hence, the providers are least influenced ( $\Delta$  Mean Rank Difference  $\approx 14$  for varied sizes groups) by the batches of advices. The requesters who give the advice to the providers can't be influenced by the batching of advices.

### c) Node Reliability Model

The standard Join methodology is made use of by peer to connect itself to a specific distributed network. The search appeal entails the peer supplicant to produce a list of nodes who have the demanded file(s) with them. RANGE indicates the count of nodes who tender a mentioned meticulous file. The peer supplicant chooses the provider with the peak status by instigating the cryptographic procedure which involves the peer supplicant making use of the Download methodology of the network for downloading the relevant file mentioned by the client, which again assists in validating the reliability, dependability and the value of the file. A proposal is then sent to the peer client between min - recommendation and max - recommendation, which are limited to the restrictions ensuring that a single implication doesn't utterly annul or radically improve the meticulousness of a supplicant. On receiving the suggestions from the client, it averages the prior received implications and incorporates the recently received ones to estimate its repute.

The factors mentioned above can be assigned values by the means of Decision Theory, Game Theory, and Probability and function  $F()$  is identified on the basis of intensity levels of menace faced by nodes in the distributed network. The function  $F()$  in this paper is described as the arithmetic average of the suggestions that are collected by the peer supplicant. The recommended node reliability copy is self governing as compared to topology of the distributed network, nodal addressing formats, bootstrap procedures, joining and leaving protocols of the nodes present and the name service.

A negative suggestion may be issued by an applicant to the peer supplicant which may turn out to be hazardous concerning its node reliability even though the supplicant actually is worthy of a positive recommendation for a specified transaction. If in a way, only positive recommendations are accepted, then it would be tougher to distinguish between new and bad peers. Hence an assumption is made here that both positive and negative proposals are permitted and a given peer would no longer cooperate with those nodes who frequently deliver negative proposals.

### d) Contract signing between peers: a signcryption approach

The entire process starts here with the employment of RSA signature algorithm [42] otherwise

known as Signcryption. At this point, the 1<sup>st</sup> user divides his private key  $d$  into  $d1$  and  $d2$  such that  $d = d1 + d2$  by following park[40]. The signature of this user has to be exchanged with the other and this signature is

$\sigma_A = h(m)^{d1} \bmod n$ . The partial signature generated by the 1<sup>st</sup> user is to assure that he has zero-knowledge base and this is done by Gennaro topology[27]. The relations we have are defective owed to network failure or router's attacks [36],[46]. But, TTP is reliable since the messages inserted reach the destination for sure but with some delay.

### i. Registration Protocol

The receiver of the information has only to record i.e. merely the recording process of the initiator with TTP is enough. He then gets a long-term voucher along with CA. After this, the following processes are done: (for our convenience, let the sender be BOB and receiver as ALICE.)

- Alice first sets an RSA modulus  $n = pq$ , where  $p$  and  $q$  are two -bit safe primes, i.e., there exist two primes  $p'$  and  $q'$  such that  $p = 2p' + 1$ ,  $q = 2q' + 1$ . After, Alice selects her random public key  $e \in_R \mathbb{Z}_{\phi(n)}^*$ , and calculates her private key  $d = e^{-1} \bmod \phi(n)$ , where  $\phi(n) = (p-1)*(q-1)$ . At last, Alice registers her public key with a CA to get her certificate  $C_A$ , which binds her identity and the corresponding pubic key  $(n, e)$  together.
- Alice randomly splits  $d$  into  $d1$  and  $d2$  such that  $d = d1 + d2 \bmod \phi(n)$  by choosing  $d1 \in_R \mathbb{Z}_{\phi(n)}^*$ , and computes  $e1 = d1^{-1} \bmod \phi(n)$ . She also generates a sample message-signature pair  $(\omega, \sigma_\omega)$ , where  $\omega \in \mathbb{Z}_n^* \setminus \{1, -1\}$ ,  $ord(\omega) \geq p'q'$  and  $\sigma_\omega = \omega^{d1} \bmod n$ . Then, Alice sends  $(C_A, \omega, \sigma_\omega, d2)$  to the TTP but keeps  $(d, d1, d2, e1)$  secret.
- The TTP first checks for the validation of Alice's certificate  $C_A$ . After that, the TTP checks that the triple  $(\omega, \sigma_\omega, d2)$  is arranged correctly. If the whole thing is in exact order as per its rules, TTP saves  $d2$  and generates a voucher  $V_A$  by computing  $V_A = \text{Sign}_{TTP}(C_A, \omega, \sigma_\omega)$ . This proves the TTP's signature on message  $(C_A, \omega, \sigma_\omega)$ , which guarantees that the TTP can issue a valid partial signature on behalf of Alice by using the secret  $d2$ .



ii. *Signature Exchange Protocol*

Before all this, a contract has to be agreed between bob and Alice and they should sign it. It should also has a deadline, and identify the Alice, Bob, and TTP.

- a) Initially, the initiator Alice has to compute her partial signature  $\sigma_1 = h(m)^{d_1} \bmod n$ , and then sends the triple  $(C_A, \omega, \sigma_\omega)$  to the responder Bob. Here,  $h(.)$  is a cryptographically secure hash function.
- b) After receiving  $(C_A, V_A, \sigma_1)$ , Bob first verifies that  $C_A$  is whether issued by CA, and  $V_A$  is Alice's voucher created by the TTP. Then, Bob checks if the identities of Alice, Bob, and the TTP are correctly mentioned as part of the contract 'm'. If all these checking are ok, Bob initiates the below interactive zero-knowledge protocol with Alice to check whether  $\sigma_1$  is Alice's valid partial signature on contact.
  - i. Then Bob selects two numbers  $i, j \in_R [1, n]$  at random, and a challenge  $c$  to Alice is sent by computing  $c = \sigma_1^{2i} \sigma_\omega^j \bmod n$ .
  - ii. Receiving the challenge  $c$ , Alice calculates the response  $r = c^e \bmod n$ . She then returns her commitment  $\bar{r} = TCcom(r, t)$  to Bob using a random number  $t$ , where  $TCcom$  is the commitment algorithm.
  - iii. After receiving the commitment  $\bar{r}$ , Bob sends Alice the pair  $(i, j)$  to acknowledge that he is done with the challenge  $c$  properly.
  - iv. Alice verifies for correct preparation of  $c$ , that is  $c \equiv \sigma_1^{2i} \sigma_\omega^j \bmod n$ . If ok, Alice withdraws his commitment  $\bar{r}$  by knowing the responses  $(r, t)$  to Bob. With this  $(r, t)$ , Bob knows  $\sigma_1$  as valid if and only if  $r \equiv h(m)^{2i} \omega^j \bmod n$  and  $\bar{r} \equiv TCcom(r, t)$ .
- c) Bob checks the  $\sigma_1$  Alice's valid partial signature and the deadline  $t$  mentioned in contract  $m$  is whether enough for resolving the dispute resolution from the TTP. Then only he sends his signature  $\sigma_B$  to Alice.
- d) After receiving  $\sigma_B$ , Alice has to check whether it is Bob's valid signature. If it is, she sends Bob the partial signature  $\sigma_2$  by computing  $\sigma_2 = h(m)^{d_2} \bmod n$ . As Bob receives  $\sigma_2$ , he sets

$\bar{\sigma}_A = \sigma_1 \sigma_2 \bmod n$ , and accepts  $\sigma_2$  as valid if and only if  $h(m)^2 = \bar{\sigma}_A^{2e} \bmod n$ . Here, Bob can receive Alice's standard RSA signature  $\sigma_A$  on message  $m$  from  $\bar{\sigma}_A$ . If all this do not happen, Bob seeks the help of TTP for connection before the expiry of the date.

#### IV. Node reliability exchange protocol

The status swapping procedure is commenced with the node supplicant when the node applicant chooses the supplicant with the highest status. This procedure requires the applicant to be represented as R and the node supplicant is represented as P. As in  $R \rightarrow P$ : X represents that the node sends a message X to the supplicant (P).  $P_{k1}$  denotes private key of node P while  $P_{k1}$  denotes public key of the peer.  $E_k(\tau)$  denotes encryption of the phase  $(\tau)$  with key K and  $E_{B_k}(X)$  symbolizes blinding phrase with a key K.  $H(\lambda)$  denotes a one way hash of the value  $\lambda$ . This procedure supposes that obtainable functions are inserting and search, but are not flexible enough for nodes which may not be proposed tag along the join and leave procedures of the network. The status swapping procedure contains the following phases:

Step 1:  $R \rightarrow P$ : RTS & IDR a REQUEST FOR TRANSACTION (RTS) is sent by the node applicant along with its own IDENTITY CERTIFICATE (IDR) to the node supplicant as it is required for authentication purposes in Step 7.

Step 2:  $P \rightarrow R$ : IDP & TID &  $E_{P_{k2}}(H(TID) \parallel RTS)$ .

The peculiar IDENTITY CERTIFICATE (IDP), the CURRENT TRANSACTION ID (TID) and the signed TID,  $E_{P_{k2}}(H(TID) \parallel RTS)$  is sent by the node supplicant wherein signed TID is essential for the supplicant to avoid duplication of the usage of the same transaction id again. The applicant also applies for this signed TID and piles it up in the network at the end of the procedure for admission to other peers.

Step 3:  $R : LTID$  (Max (Search(PK1  $\parallel$  TID))). The value of the LAST TRANSACTION ID (LTID) that was used by the supplicant is gathered by the node applicant who then combines the public key P of the node supplicant along with the string TID and a search operation is carried out. Any node present in the network responds only when it has the relevant TID that is specified by the applicant and the node applicant chooses the highest TID out of all the TIDs received. The highest TID value becomes the LTID. It is certainly possible that the node supplicant may conspire with the node who piled up its last LTID and may modify it, but this is impossible as the applicant registers relevant information.

Step 4: R : IF(LTID  $\geq$  TID)GO TO Step 12 Foul play is presumed if the value of LTID initiated by the node applicant is originally from some other random transaction and applicant jumps to Step12.

Step 5: R  $\rightarrow$  P: Past Recommendation Request & r. If the step 4 check gives successful results, then applicant requests the supplicant for the earlier received proposals. If the current transaction being performed is, say Nth transaction, the applicant makes a head-on request for N-1th,N-2th,...,N-nth proposals where  $r < N$ . The node applicant is solely responsible for deciding the value of r and is considered to be directly proportional to the applicant's venture in the transaction.

Step 6: P  $\rightarrow$  R: CHAIN,  $E_{p_{K2}}$  (CHAIN)

CHAIN = ({RE  $C_{N-1}$  ||  $E_{Z_{N-1K2}}$  (H(RE  $C_{N-1}$  ))} ||  
 {RE  $C_{N-2}$  ||  $E_{Z_{N-2K2}}$  (H(RE  $C_{N-2}$ , RE  $C_{N-1}$  ))} ||  
 {RE  $C_{N-3}$  ||  $E_{Z_{N-3K2}}$  (H(RE  $C_{N-3}$ , RE  $C_{N-2}$  ))} ||  
 {RE  $C_{N-4}$  ||  $E_{Z_{N-4K2}}$  (H(RE  $C_{N-r}$ , RE  $C_{N-r-1}$  ))})

The earlier received proposals RE  $C_{N-1}$ , RE  $C_{N-2}$ , ..., RE  $C_{N-3}$  which were provided by nodes  $Z_{N-1}$ ,  $Z_{N-2}$ , ...,  $Z_{N-3}$  is sent by the supplicant. The CHAIN is signed so as to enable the applicant to hold supplicant responsible for the chain. The supplicant can, in no way, change the proposals that have been assessed by the earlier applicants. Consider an applicant (say  $Z_1$ ) has signed both the (i th) and the previous (i -1th) recommendation using its private key  $Z_{K2}$ , as  $E_{Z_{K2}}$  (H(RE  $C_{N-3}$  || RE  $C_{N-(i-1)}$ )), in no way can a supplicant alter the CHAIN.

Step 7: R : Result=Verify(RE  $C_{N-1}$  ;RE  $C_{N-2}$

RE  $C_{N-r}$ )

If Result != Verified GO TO STEP 12

A simple public key cryptography protocol is employed by an applicant to authenticate the CHAIN. The authentication process is easier when a supplicant possesses certificates of all the nodes with whom it had connections earlier. In case it doesn't have one, it accumulates it from the supplicant itself. The provider had obtained its requester's certificate in Step 1. Liar farms (specified in Section 3.2, paragraph 2) are checked for by the applicant. The applicant jumps to Step 12 in case the authentication process fails.

Step 8: Contract signing between node selected under node reliability check and node that requesting the service

Signature exchange protocol will get into action between Peer "SRP" that requesting the service and Peer "SPP" that selected as service provider by node reliability check.

Initially, the initiator SRP has to compute her partial signature  $\sigma_1 = h(m)^{d_1} \bmod n$ , and then sends the triple  $(C_A, \omega, \sigma_\omega)$  to the responder SPP. Here,  $h(.)$  is a cryptographically secure hash function. After receiving  $(C_A, V_A, \sigma_1)$ , SPP first verifies that  $C_A$  is whether issued by CA, and  $V_A$  is SRP's voucher created by the TTP. Then, SPP checks if the identities of SRP, SPP, and the TTP are correctly mentioned as part of the contract 'm'. If all these checking are ok, SPP initiates the below interactive zero-knowledge protocol with SRP to check whether  $\sigma_1$  is SRP's valid partial signature on contract. Then SPP selects two numbers  $i, j \in_R [1, n]$  at random, and a challenge  $c$  to SRP is sent by computing  $c = \sigma_1^{2i} \sigma_w^j \bmod n$ . Receiving the challenge  $c$ , SRP calculates the response  $r = c^e \bmod n$ . She then returns her commitment  $\bar{r} = TCcom(r, t)$  to SPP using a random number  $t$ , where  $TCcom$  is the commitment algorithm. After receiving the commitment  $\bar{r}$ , SPP sends SRP the pair  $(i, j)$  to acknowledge that he is done with the challenge  $c$  properly. SRP verifies for correct preparation of c, that is  $c \equiv \sigma_1^{2i} \sigma_w^j \bmod n$ . If ok, SRP withdraws his commitment  $\bar{r}$  by knowing the responses  $(r, t)$  to SPP. With this  $(r, t)$ , SPP knows  $\sigma_1$  as valid if and only if  $r \equiv h(m)^{2i} \omega^j \bmod n$  and  $\bar{r} \equiv TCcom(r, t)$ . c). SPP checks the  $\sigma_1$  SRP's valid partial signature and the deadline  $t$  mentioned in contract  $m$  is whether enough for resolving the dispute resolution from the TTP. Then only he sends his signature  $\sigma_B$  to SRP. After receiving  $\sigma_B$ , SRP has to check whether it is SPP's valid signature. If it is, she sends SPP the partial signature  $\sigma_2$  by computing  $\sigma_2 = h(m)^{d_2} \bmod n$ . As SPP receives  $\sigma_2$ , he sets  $\sigma_A = \sigma_1 \sigma_2 \bmod n$ , and accepts  $\sigma_2$  as valid if and only if  $h(m)^2 = \sigma_A^{2e} \bmod n$ . Here, SPP can receive SRP's standard RSA signature  $\sigma_A$  on message  $m$  from  $\sigma_A$ . If all this do not happen, SPP seeks the help of TTP for connection before the expiry of the date.

Step 9: P  $\rightarrow$  R : File or Service

The file or service is afforded as per the obligation specified concerning search operation performed for the supplicants.

Step 10: R  $\rightarrow$  P : B1 =  $E_{K_A}$  (REC || TID ||  $E_{R_{K2}}$  {H(REC, || TID)})

A BLINDING KEY ( $K_a$ ) is produced by an applicant on receiving the service, who then combines the RECOMMENDATION (REC) and the TRANSACTION ID (TID) it had received in Step 2 and signs it. Consequently, the signed proposal is blinded along with the blinding key,  $K_a$ . This is done in order to entrust the supplicant to the proposal received before it actually knows the value, lest it disowns it on recognizing that it is low. It is also involves the fact that the supplicant made use of TID in a blinded suggestion from the node applicant, which is also authenticated by the applicant itself. The blinded proposal includes the Chain that is consequently used by the supplicant to certify its status to some other applicant.

Step 11:

- a.  $P \rightarrow R : B1 \parallel E_{P_{K_2}}(H(B1), \text{nonce}), \text{nonce}$
- b.  $R \rightarrow P : K_a$

A NONCE is sent by the supplicant after signing the proposal even though it is unable to see the proposal and acknowledges it back to the applicant, who then authorizes the signature and sends blinding key  $K_a$  to the supplicant to unblind the received string in Step10a and confirms the received proposal.

Step 121: Insert

$$(IDR; \{REC \parallel TID \parallel E_{R_{K_2}} \{H(REC) \parallel H(TID)\}\})$$

The proposal assigned to the supplicant (REC), the transaction id (TID), and its own identity certificate is verified by the applicant and is then accumulated in the network using Insert methodology of the distributed network which marks the end of the transaction.

Step 13: Step 12 is concerning the methodology executed by an applicant when foul play is anticipated.

ABORT PROTOCOL

R: Insert (IDR; {CHAIN  $\parallel$  TID  $\parallel$   $E_{R_{K_2}} \{H(CHAIN) \parallel H(TID)\}$ })

If the authentication process in Step7 fails, the applicant takes the CHAIN that was verified b the supplicant and also the TID is taken into consideration after which, it is signed and the Insert methodology is preferred to be made use of to insert the chain and also its own identity certificate into the network. Subsequently, any suitable applicant will be able to confirm with the statistics of the failed authentication efforts and a MIN RECOMMENDATION for that TID is presumed for the supplicant. Fafe proposals cannot be encouraged to be inserted into the network as TID is to initiated that is verified by the supplicant. If an applicant reaches Step 12 from Step 4 without any possible hindrances, it will then apply for the Chain form the supplicant and will then afterward execute

R: Insert(IDR, {CHAIN  $\square$  TID  $\square$  {H(TID  $\square$  RTS))}).

## V. Analysis of the protocol

Only a single search request is supposed to be commenced in the network so as to gather the already received proposals that were previously received by the supplicant. Also able to prevent the tampering node reliability provided by SRP to SPP by nodes that in path. This process is required the accountability of tackling the issue of unbalanced nature of availability of nodes in the network, which is measured to be a main subject concerning distributed networks.

1. The supplicant unintentionally forwards the wrong TID in Step 2. Consider that id which the supplicant forwards as TID and the LTID be the last Transaction ID for the supplicant. The value of TID is always supposed to be equivalent to LTID + 1. If in case of  $TID' > LTID+1$ , there arises a situation wherein there will be inexplicable misplaced proposals. If again in case of  $TID' < LTID+1$ , then the supplicant will be caught up with in the Step 4 of the procedure, as the last id issued and used by the supplicant was made public and accessible to all the peers. The value of TID is considered as 0 if a node is for the first time donning the role of a supplicant.
2. The transaction in Step 8 will not be terminated by the supplicant. A supplicant is allowed to abandon the transaction after providing the applicant with the requested requisite information in Step 8 and also can abandon the transaction after Step 9. In both the cases, there is an absence of a proposal by the supplicant for the transaction id TID. The proposal in Step 11 can be liberated by the applicant provided the supplicant fails to verify and sign the blinded proposal, without acquiring the supplicant's signature. In the next transaction, precisely TID+1, the supplicant again fails to illustrate the proposal for that relevant transaction, TID to the transaction's applicant, TID+1 and hence the new applicant entrusts itself with the job of scanning the network making use of Search methodology for TID. In case TID is found, the suggested proposals are also found out pertaining to the suppliant in the transaction. The applicant will then be responsible as the TID would by then have been signed b the supplicant, who will have to acknowledge the proposal as it comprises the signature of the supplicant, TID &  $E_{P_{K_2}}(H(TID))$ . A minimal suggestion TID is presented to the supplicant by the node applicant in the absence of the availability of the required proposal. If in Step 10, the supplicant acknowledges the signed blinded proposal B1 &  $E_{P_{K_2}}(H(B1))$ , the applicant refuses to send the key,  $K_a$  and directs itself to Step 10, missing all the requisite steps, and then the supplicant scans the entire network and acquires the verified proposal of

the applicant. If an applicant skips or fails to execute Step 10, then in the upcoming transaction TID+1, LTID is looked for by the new applicant and fails in his endeavor. Hence, TID can be considered as terminated and the next transaction can be continued with the transaction id provided, TID.

3. Collusion by rogues or liar farms. All status systems are prone to complicity on account of its nature. It is possible for two or more liar farms to combine and conspire in order to augment each other's status. The influence of the conspiracy can be alleviated by classifying proposals on the basis of personage *identities*, substantiating agencies etc. The list of conspirators can be circulated, thereby, guarding the remaining nodes from an possible attack. Peers when recognized as conspirators will not be permitted to get back into the stream of network and hence they have an impetus next to conspiracy. The series of proposals of the plotters will aid in offering support that few nodes are conspiring, thereby, protecting good nodes and from the intrusion of bad nodes into the network.
4. Multiple requesters and concurrency. A supplicant in the presently used procedure will not be provided with the facility of making use of the same identity in the synchronized communication. The first option for process intensification is that the supplier identifies and familiarizes all its applicants with each other. As a result, the verification process performed in Step 4 is performed amidst a group of applicants and results are arranged in accordance with the fact that TID dissimilarity needs to be initiated due to more number of applicants. After integrating the augments, there would be a bi party procedure that would still be prevalent where the cluster of applicants is considered to the second party while the supplicant is supposed to be the first party. The figure 1 explores the ability of the proposed model to prevent the false node reliability submitted by unauthorized nodes that acts as a service request node SRP.

We can observe that contract signing by signcryption approach is most effective to prevent the node reliability tampering attacks. Even node communication with contract signing also victimized few times but victimization occurred due to contract signing breakage. Hence if contract sign is alive then attacked to tamper the node reliability is almost null. The figure 2 confirms the stable growth in execution time when considers this contract signing process, which was compared with node communication process without contract signing.

Hike at node communication execution time that is negligible when consider the improvement in prevention of node reliability tampering attack attempts.

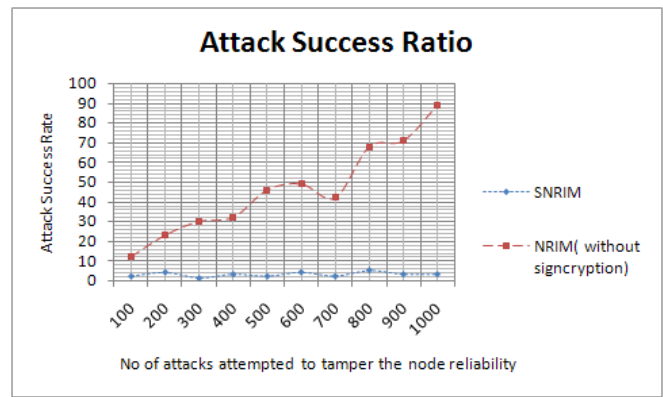


Fig. 1 : Attack success rate on NRIM and SNRIM

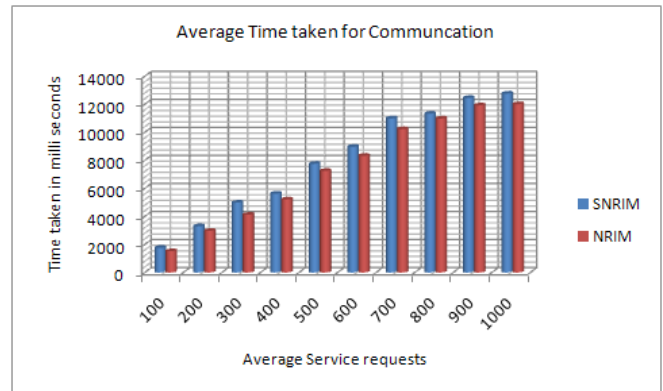


Fig. 2 : Average time taken to finish service request in SNRIM and NRIM

## VI. Conclusion

Here in this paper we proposed a signcryption based contract signing for node communication based on node reliability check. The results are evident that proposed two way node reliability checking model is effective to avoid the node reliability tampering attack efforts. The planned model is screening a little hike in average process time of node communication, which can be negligible in the context of node reliability tampering attack avoidance. In future we plan to find a solution to avoid the contract sign breaching.

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# GSM Based Operating of Embedded System Cloud Computing, Mobile Application Development and Artificial Intelligence Based System

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**Abstract** - The purpose of this paper is to identify and explore the challenges for potential solutions in the field of Mobile Application, Cloud Computing, Artificial Intelligence, Robotics and Home – made Devices (Television, Refrigerator, Air Conditioner, Air Cooler, Mixer Grinder) in Embedded Systems. This paper is an attempt to introduce the reader into the world of GSM based Operating of Embedded Systems in voice based talking GSM technology and its applications (for updating the new technologies in old device) in the industry of home – made appliances and devices in Embedded Systems.

The objective of the series will be a general discussion of GSM based new operating technologies for Mobile Applications Development and Mobile Computing in terms of Artificial Intelligence. Its application will working from non – mobile devices in home - made appliances and robotics.

**Keywords** : *Cloud Computing, Mobile Application Development, Artificial Intelligence, Embedded Systems, Robotics, Home – Made Appliances.*

**GJCST-E Classification** : C.3



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## I. INTRODUCTION

With the advancement in technology [1] we can create and developing the new technologies in the operating of mobile application development in non – mobile devices. The technologies of Information Technology are also fast developed in the field of Mobile Communication and Field of Electronics.

There are various technologies present which become to easier the daily life of human people. This paper is an idea for making and giving the operating features of embedded systems through Mobile Computing and Mobile Application Development [1,5] by using the concept of Artificial Intelligence. This concept was used for controlling the embedded systems in Robotics and Home Made Appliances. The application of this project [1] in terms of paper has given

a new generations of home - made devices in mobile application of cloud computing.

## II. Principle

The project of this principle is used for controlling the embedded systems through taking the application of Robotics and Home – Made Appliances. This principle is also useful for controlling the home – made appliances and robots through voice talking based GSM Technology [3] with updating the new technologies in old devices for making the WAP connection through cloud computing [4] for operating the system. This technology is also useful for developing the principle of Artificial Intelligence at the updating of new technologies. The positive effect of this point is useful for less repairing and automatic mode repairing [2] of embedded systems, robotics and home – made appliances through updating the device or cloud computing system. This principle also gives the High Speed Internet Connectivity [1] through Cloud Computing System. This technology will also helpful for increased production [2] of home – made appliances in developing countries.

## III. Practical applications

This is the project for generating the concept of cloud computing [1] through the updating of various devices like Television, Refrigerator, Air Conditioner etc. and getting the High Speed Internet Connectivity for another devices. This project also generates the [4] concept of Artificial Intelligence through by giving the concept of Automatic Mode Repairing or Updating of various devices like Television, Refrigerator, Air Conditioner etc. It also generates the concept of Mobile Application Development through our devices in Embedded Systems. We have wanted to make a two Embedded Systems:-

1. Server
2. Client

Both of these two systems are connected through Internet Connectivity by using the concept of [1] ABP Software or any Internet Coding Software in Embedded Systems.

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When we will send any information to the client through server based Embedded Systems. The server information will reach and operation will perform to the client based Embedded Systems. When the operations will have performed, the client based Embedded Systems will send the message through server to "Operation is Successful."

So, both the client and server embedded systems are to be connected in High Speed Internet Connectivity and GSM Communication Systems. This project also gives the concept of Automatic Mode Repairing [2] and Updating of New Technologies in various devices based Embedded Systems. This is the technology for designing the embedded system [1] in Television, Refrigerator, Air Conditioner and various devices. This Embedded System also giving the applications of Robotics System. This system enables:

1. Any Mobile Phone is not using in our project for making GSM Communication Systems.
2. It also requires two Embedded Systems connected through the Internet Connectivity and GSM Communication Systems
3. LCD's are also available for both making the Client and Server based Embedded Systems.



Flow Chart Diagram of Embedded System

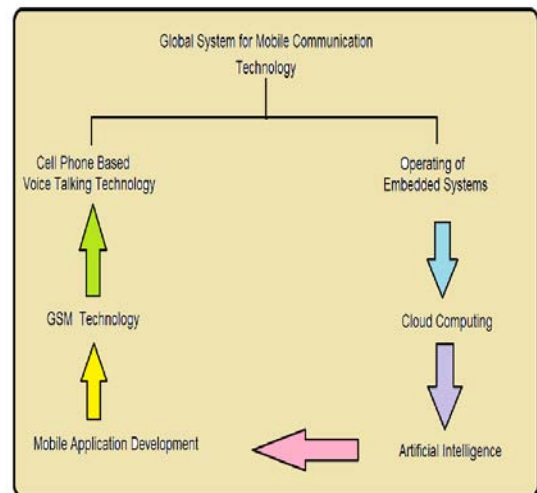
This Embedded System has giving the future applications of Home-made Appliances for designing and updating the system. Although this application is possible in Robotics System and Home- Made Appliances. This technology has also used in Mobile and Cell Phone Industries. It has reduced the Cell Phone Radiation through Cloud Computing System. This

technology also gives the free High Speed Internet Connectivity and Internet Phoning for Home – Made Appliances. The concept arises for the best idea and few years of research in GSM technologies for Home-made Appliances.

#### IV. GSM NETWORKING ARCHITECTURE

The GSM Networking indicates that Global System for Mobile Communication Networking. This architecture represents the many features and applications on daily life of human people. GSM is a digital mobile telephony system [1,9] that is widely used in Europe and other parts of the world. GSM uses a variation of Time Division Multiple Access (TDMA) and it is the most widely used of the three digital wireless telephony technologies (TDMA, GSM and CDMA). GSM digitizes and compresses data, then sends it down a channel with two other streams of data for making the communication. It operates at either [1] the 900 MHz or 1800 MHz frequency band. This networking architecture is also useful and connects the devices with million distances of the world. This networking architecture also connected to the many users and millions of devices.

Networking Architecture of GSM Based Operating of Embedded System



#### V. CLOUD COMPUTING

Cloud Computing refers to the delivery of computing and storage capacity [6,7] of a service. The name comes from the use of clouds as an abstraction for the complex infrastructure it contains in system diagrams. Cloud computing entrusts services with a user's data, software and computation [5] over a network. It has considerable overlap with software as a service. Cloud computing relies on sharing of resources to achieve coherence and economies of scale similar to a utility (like the electricity grid) over a network.

The cloud computing also connects and establishes the network of operating many devices [1] through a server access portal. This technology is also

making the cloud for controlling and operating the many devices.

## VI. MOBILE APPLICATION DEVELOPMENT

It is the process by which application software is developed for low-power handheld devices [6] such as personal digital assistants, enterprise digital assistants or mobile phones. These applications are either pre-installed on phones during manufacture, can be downloaded by customers from various mobile software distribution platforms, or web applications delivered over HTTP which use server-side or client-side processing (e.g. JavaScript) to provide an "application-like" experience within a Web browser. The mobile application is very useful [10] and developed in the operating of mobile phones. The mobile application is very famous for generating the new technologies and operating features of mobile device.

## VII. ARTIFICIAL INTELLIGENCE

It is the intelligence of machines and the branch of computer science [3] that aims to create it. It defines the field as "the study and design of intelligent agents" where an intelligent agent is a system that perceives its environment and takes actions that maximize its chances of success. Artificial intelligence has been the subject of optimism, but has also suffered setbacks and, today, has become an essential part of the technology industry, providing the heavy lifting for many of the most difficult problems in computer science. This device is the basic principle of Artificial Intelligence. The Artificial Intelligence is also useful for developing his sense [4] in any system of machine. This project is also developing the artificial intelligence for giving the updating of new technologies through which it become automatic mode repairing in home – made device and embedded system.

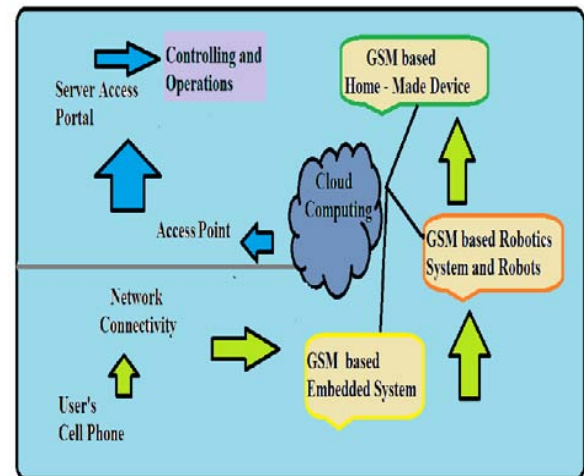
## VIII. WORKING IN EMBEDDED SYSTEM

The project of this paper is to make a wireless GSM connection [1] in between user and embedded system of home - made devices (Television, Refrigerator, Air Conditioner etc) and Robotics.

This device presents a sensor from Artificial Intelligence for controlling of Embedded Systems in Voice Talking Technology based GSM System. This technology developed a new generation for developing WAP connection on cloud computing [7,8] with operations of home – made devices. Its application is important for updating and controlling the operations or work processing of home – made devices. This GSM technology based device is developing the many work stage in operating the Embedded System by making the main application of homemade appliances.

These work stages include:

- To establish the GSM connection in Embedded Systems.
- To establish the voice talking technology based GSM system.
- To establish the cloud computing for controlling the operation of Embedded Systems.
- To establish the WAP connection for updating the operation of mobile application in home – made appliances through Mobile Cloud Computing.

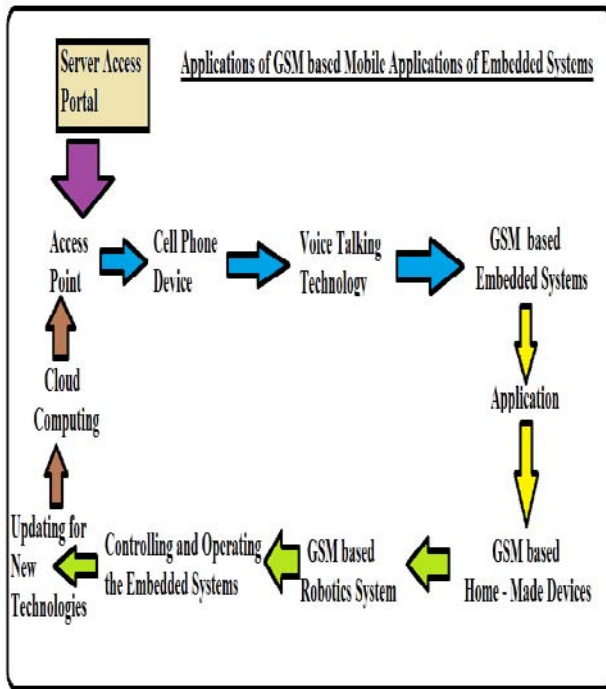


Working Process of GSM based Operating Embedded System

## IX. APPLICATION

The applications of this project in terms of research paper developed a new technology for using the mobile application development [6] in non – mobile devices like Robotics and Home – Made Devices. This technology developed the operations of current – voltage power supply, controlling and operating the all parts and connecting through new technologies. Used Applications of home – made devices in Television, Refrigerator, Air Conditioner, Air Cooler, Mixer Grinder is controlling all the parts and current – voltage power supply for establishing the cloud computing [7] in various devices of networks. This technology will also developing the principle of Artificial Intelligence for operating and automatic mode repairing in home – made appliances and embedded system.





## X. EMBEDDED SYSTEMS

An Embedded System is a computer designed system for specific control function within a larger system [2] often with real time computing constraints. It is embedded as a part of completed device often including hardware and mechanical parts. Embedded Systems [8] control many devices in common use today. Embedded Systems contain processing cores that are typically either Microcontroller or Digital Signal Processor. The designing of Embedded Systems is to make a computer through computing of device.

## XI. ROBOTICS

The world we interact in everyday and the technology that we [9] utilize are making the new technology of Robotics in Embedded System. The Robotics System provides the engineering foundation for the design, implementation and analysis of embedded system with an emphasis in autonomous robotics system. It creates the many features [10] of mechanical design, control electronics, embedded programming machine and adaptive programming development.

*"The technology for an automatic device that perform functions normally describe to human or a machine in the form of human people."*

## XII. HOME – MADE APPLIANCES

The Home – Made Appliance are using in home and easy the daily work of human people. Home – Made Appliances also become the easier and comfortable life of human people. The work applications [4] of home – made appliances:

- Television gives the World of Entertainment.
- Refrigerator gives the preservation of food, making ice and cold water.
- Air Conditioner gives the cold room at longer time.
- Air Cooler gives the cool air in every season of time.
- Mixer Grinder gives the various spices for grinding and many things.

## XIII. CONCLUSION

There are various technologies developed in the field of electronics and mobile application development. This paper is an attempt for developing the application of mobile in embedded systems. This technology will also useful for making the mobile application based home – made appliances by giving the [3] controlling principle of Artificial Intelligence. This principle is also useful for robotics through cloud computing [7] in which user can already access his robot through cloud computing. The application of mobile in robotics system is operating the function of robots. It will also give the concept of Artificial Intelligence for operating and updating the Embedded System.

This technology is also give the concept of GSM Based Controlling Device through Voice Talking Technology [1] in which human people is connecting and controlling the operation of electronic device [2] and home – made appliance with any part of the world. This paper is introducing the concept of computer based technology in Home – Made Appliances (Television, Refrigerator, Air Conditioner, Air Cooler and Mixer Grinder) and Robotics System. This technology will also give its application and future aspects of computer based home – made appliances in embedded system.

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Approach:

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- If use of a definite type of tools.
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The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.

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#### Approach

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- Give details all of your remarks as much as possible, focus on mechanisms.
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- Try to present substitute explanations if sensible alternatives be present.
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- Recommendations for detailed papers will offer supplementary suggestions.

#### Approach:

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<b>Methods and Procedures</b>	Clear and to the point with well arranged paragraph, precision and accuracy of facts and figures, well organized subheads	Difficult to comprehend with embarrassed text, too much explanation but completed	Incorrect and unorganized structure with hazy meaning
<b>Result</b>	Well organized, Clear and specific, Correct units with precision, correct data, well structuring of paragraph, no grammar and spelling mistake	Complete and embarrassed text, difficult to comprehend	Irregular format with wrong facts and figures
<b>Discussion</b>	Well organized, meaningful specification, sound conclusion, logical and concise explanation, highly structured paragraph reference cited	Wordy, unclear conclusion, spurious	Conclusion is not cited, unorganized, difficult to comprehend
<b>References</b>	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring



# INDEX

---

## A

Academic · 25  
Adaptive · 14, 16, 20, 23, 24  
Aerospace · 12  
Algorithm · 6, 10  
Appliances · 43, 45, 46, 49, 50  
Artificial · 43, 44, 47, 48, 49, 50  
Authentic · 1, 4, 31  
Avoidance · 40

---

## B

Bellman · 11

---

## C

Cellular · 1, 3, 4, 5  
Concerning · 3, 27, 33, 36, 37  
Coverage · 6, 7, 8, 9, 10

---

## E

Embarrassment · 3  
Embedded · 43, 44, 45, 46, 47, 48, 49, 51  
Encryption · 1  
Establish · 4, 31, 48  
Exposure · 8, 9, 10

---

## G

Gathered · 18, 35  
Guarantees · 34

---

## I

Infrastructure · 46  
Instrumentation · 51  
Intelligence · 14, 23, 47  
Intelligence · 14, 43, 44, 47, 48, 49, 50  
Intermediate · 16, 17, 21

---

## M

Microcontroller · 1, 49

---

## P

Pheromone · 14, 17, 18, 19, 20, 22  
Prentice · 23  
Provenance · 27

---

## R

Reinitiates · 17  
Reliability · 27, 28, 29, 31, 33, 35, 36, 37, 39, 40  
Retransmissions · 22  
Revolutionizing · 4  
Robotics · 43, 49  
Robotics · 43, 45, 47, 48, 49, 50

---

## S

Scalability · 41  
Sensors · 6, 8, 10, 12  
Signcryption · 27, 33  
Signing · 27, 29, 31, 33, 35, 36, 37, 39, 41, 42  
Software · 1, 44

---

## T

Technology · 1, 3, 4, 5, 12, 14, 43, 44, 47, 50, 51  
Topology · 14, 16, 23

---

## U

Unicast · 14

---

## V

Verification · 27  
Verified · 37  
Voronoi · 9, 10

---

## W

Wireless · 6, 7, 12, 14, 23, 25  
Workshop · 5, 12



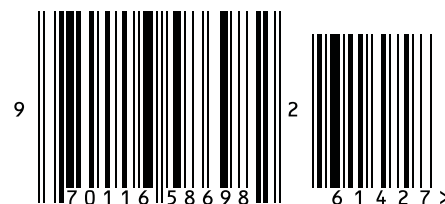
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